

Generalization of the Ball-Collision Algorithm

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Proposing a code-based cryptosystem

- Structural Attacks
- Nonstructural Attacks

Have to consider Information Set Decoding (ISD)

Proposing a code-based cryptosystem

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Have to consider Information Set Decoding (ISD)

1978 Berlekamp, McEliece and van Tilborg: Decoding a random linear code is NP-complete

Problem (Syndrome decoding problem)

Given a parity check matrix H of a (binary) code of length n and dimension k and a syndrome s :

$$s = Hx^\top \in \mathbb{F}_2^{n-k}$$

and the error correction capacity t , we want to find $e \in \mathbb{F}_2^n$ of weight t such that

$$s = He^\top.$$

ISD algorithms and syndrome decoding problem

- Syndrome decoding problem is equivalent to the decoding problem and

Problem (Decoding problem)

Given a generator matrix G of a (binary) code of length n and dimension k and a corrupted codeword c :

$$c = mG + e \in \mathbb{F}_2^n$$

and the error correction capacity t , we want to find $e \in \mathbb{F}_2^n$ of weight t .

- equivalent to finding a minimum weight codeword, since in $\mathcal{C} + \{0, c\}$ the error vector e is now the minimum weight codeword.

Notation

Let $c \in \mathbb{F}_q^n$ and $A \in \mathbb{F}_q^{k \times n}$, let $S \subset \{1, \dots, n\}$, then we denote by c_S the restriction of c to the entries indexed by S and by A_S the columns of A indexed by S . For a code $\mathcal{C} \subset \mathbb{F}_q^n$, we denote by

$$\mathcal{C}_S = \{c_S \mid c \in \mathcal{C}\}.$$

Definition (Informationset)

Let $\mathcal{C} \subset \mathbb{F}_q^n$ be a code of dimension k . If $I \subset \{1, \dots, n\}$ of size k is such that

$$|\mathcal{C}| = |\mathcal{C}_I|,$$

then we call I an information set of \mathcal{C} .

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Let G be the $k \times n$ generator matrix of \mathcal{C} . If $I \subset \{1, \dots, n\}$ of size k is such that G_I is invertible, then I is an informationset of \mathcal{C} .

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Let H be the $(n - k) \times n$ parity check matrix of \mathcal{C} . If $I \subset \{1, \dots, n\}$ of size k is such that H_{I^c} is invertible, then I is an informationset of \mathcal{C} .

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1962 Prange proposes the first ISD algorithm.

Assumption: All t errors occur outside of the information set.

Input: $H \in \mathbb{F}_2^{n-k \times n}$, $s \in \mathbb{F}_2^{n-k}$, $t \in \mathbb{N}$

Output: $e \in \mathbb{F}_2^n$, $wt(e) = t$ and $He^T = s$.

- 1 Choose an information set $I \subset \{1, \dots, n\}$ of size k .
- 2 Find an invertible matrix $U \in \mathbb{F}_2^{n-k \times n-k}$ such that $(UH)_I = A$ and $(UH)_{I^c} = \text{Id}_{n-k}$.
- 3 If $wt(Us) = t$, then $e_I = 0$ and $e_{I^c} = Us$.
- 4 Else start over.

- 1 Choose an information set $I \subset \{1, \dots, n\}$ of size k .

Let us assume for simplicity that $I = \{1, \dots, k\}$.

Prange's algorithm

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$$UH = \begin{pmatrix} A & \text{Id}_{n-k} \end{pmatrix},$$

hence

$$UHe^\top = \begin{pmatrix} A & \text{Id}_{n-k} \end{pmatrix} \begin{pmatrix} 0 \\ e_{I^c} \end{pmatrix} = Us.$$

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From which we get the condition $e_{I^c} = Us$.

The cost of an ISD algorithm is given by the product of

- the cost of one iteration,
- inverted success probability = average number of iterations needed.

The success probability is given by the weight distribution of the error vector.

Example (Success probability of Prange's algorithm)

$$\binom{n-k}{t} \binom{n}{t}^{-1}.$$

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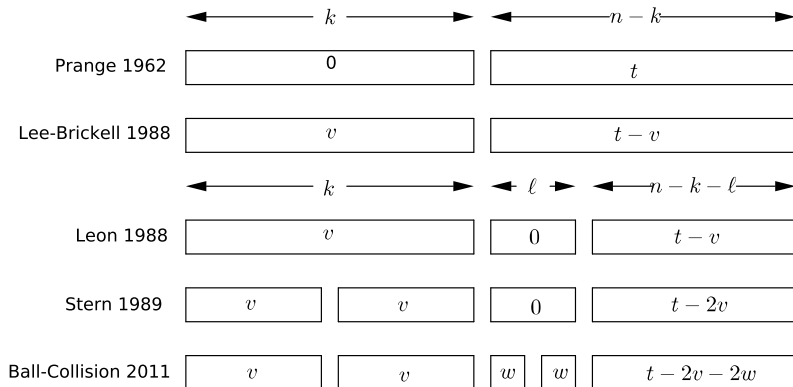
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Example (Success probability of Prange's algorithm)

$$\binom{n-k}{t} \binom{n}{t}^{-1}.$$

Improvements Overview



Ball-collision Algorithm

Algorithm 1 Ball-collision over \mathbb{F}_q

Input: The $(n - k) \times n$ parity check matrix H , the syndrome $s \in \mathbb{F}_q^{n-k}$ and the positive integers $p_1, p_2, q_1, q_2, k_1, k_2, \ell_1, \ell_2 \in \mathbb{Z}$, such that $k = k_1 + k_2$, $p_i \leq k_i$, $q_i \leq \ell_i$ and $t - p_1 - p_2 - q_1 - q_2 \leq n - k - \ell_1 - \ell_2$.

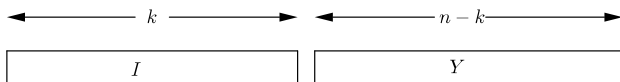
Output: $e \in \mathbb{F}_q^n$ with $He^T = s$ and $w(e) = t$.

- 1: Choose an information set $I \subseteq \{1, \dots, n\}$ of H of size k .
 - 2: Partition I into two disjoint subsets X_1 and X_2 of size k_1 and $k_2 = k - k_1$ respectively.
 - 3: Partition $Y = \{1, \dots, n\} \setminus I$ into disjoint subsets Y_1 of size ℓ_1 , Y_2 of size ℓ_2 and Y_3 of size $\ell_3 = n - k - \ell_1 - \ell_2$.
 - 4: Find an invertible matrix $U \in \mathbb{F}_q^{(n-k) \times (n-k)}$, such that $(UH)_Y = \text{Id}_{n-k}$ and $(UH)_I = \begin{bmatrix} A_1 \\ A_2 \end{bmatrix}$, where $A_1 \in \mathbb{F}_q^{(\ell_1 + \ell_2) \times k}$ and $A_2 \in \mathbb{F}_q^{\ell_3 \times k}$.
 - 5: Compute $Us = \begin{bmatrix} s_1 \\ s_2 \end{bmatrix}$, where $s_1 \in \mathbb{F}_q^{\ell_1 + \ell_2}$ and $s_2 \in \mathbb{F}_q^{\ell_3}$.
 - 6: Compute $S = \{(A_1(\pi_I(x_1)) + \pi_{Y_1 \cup Y_2}(y_1), x_1, y_1) \mid x_1 \in \mathbb{F}_q^{n-k}(X_1), wt(x_1) = v_1, y_1 \in \mathbb{F}_q^{n-k}(Y_1), wt(y_1) = w_1\}$,
 - 7: Compute $T = \{(-A_1(\pi_I(x_2)) + s_1 - \pi_{Y_1 \cup Y_2}(y_2), x_2, y_2) \mid x_2 \in \mathbb{F}_q^{n-k}(X_2), wt(x_2) = v_2, y_2 \in \mathbb{F}_q^{n-k}(Y_2), wt(y_2) = w_2\}$.
 - 8: **for** $(v, x_1, y_1) \in S$ **do**
 - 9: **for** $(v, x_2, y_2) \in T$ **do**
 - 10: **if** $w(-A_2(\pi_I(x_1 + x_2)) + s_2) = t - p_1 - p_2 - q_1 - q_2$ **then**
 Output: $e = x_1 + x_2 + y_1 + y_2 + \sigma_{Y_3}(-A_2(\pi_I(x_1 + x_2)) + s_2)$
 - 11: **else** go to Step 1 and choose new information set I .
-

Ball-collision Algorithm

- 1 Choose an information set I .

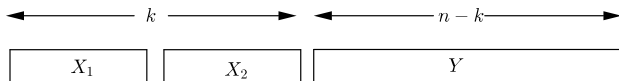
Let us assume for simplicity that $I = \{1, \dots, k\}$.



Ball-collision Algorithm

- 1 Choose an information set I .
- 2 Partition I into X_1 and X_2 .

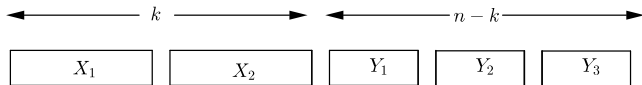
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- 3 Partition Y into Y_1, Y_2, Y_3 .

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Ball-collision Algorithm

- 1 Choose an information set I .
- 2 Partition I into X_1 and X_2 .
- 3 Partition Y into Y_1, Y_2, Y_3 .
- 4 Bring H in systematic form.

$$UHe^T = \begin{pmatrix} A_1 & \text{Id}_{\ell_1+\ell_2} & 0 \\ A_2 & 0 & \text{Id}_{\ell_3} \end{pmatrix} \begin{pmatrix} e_1 \\ e_2 \\ e_3 \end{pmatrix} = \begin{pmatrix} s_1 \\ s_2 \end{pmatrix} = Us.$$

We get the conditions

$$A_1 e_1 + e_2 = s_1,$$

$$A_2 e_1 + e_3 = s_2.$$

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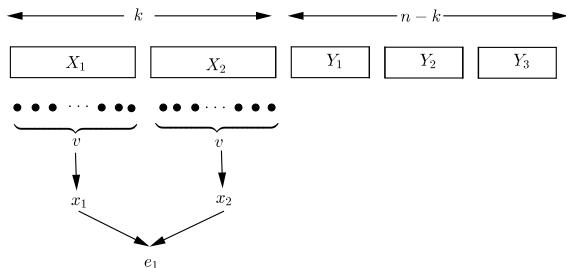
$$A_2 e_1 + e_3 = s_2.$$

Assumptions:

- a e_1 has support in $I = X_1 \cup X_2$ and weight $2v$
- b e_2 has support in $Y_1 \cup Y_2$ and weight $2w$
- c e_3 has support in Y_3 and weight $t - 2v - 2w$

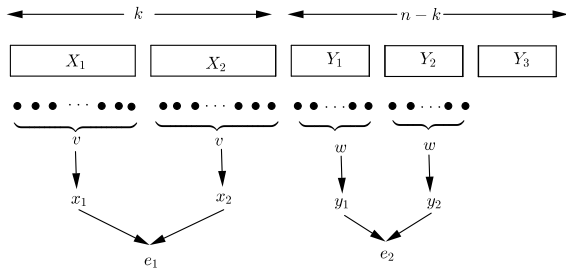
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$$A_1 e_1 + e_2 = s_1, \quad (1)$$

$$A_2 e_1 + e_3 = s_2. \quad (2)$$

For condition (1):

go through all choices of e_1 and e_2 and check with collision if (1) is satisfied.

For condition (2):

define $e_3 = s_2 - A_2 e_1$ and check if e_3 has weight $t - 2v - 2w$.

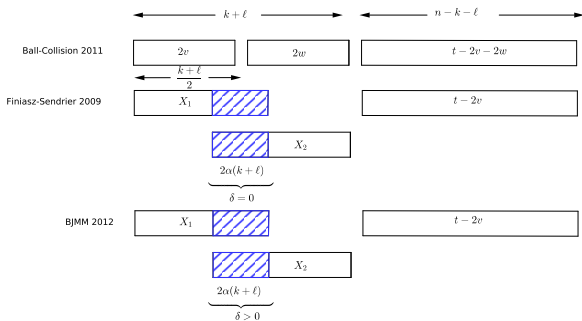
Success probability:

$$\binom{\lfloor k/2 \rfloor}{v} \binom{\lceil k/2 \rceil}{v} \binom{\lfloor \ell/2 \rfloor}{w} \binom{\lceil \ell/2 \rceil}{w} \binom{n-k-\ell}{n-2v-2w} \binom{n}{t}^{-1}.$$

Idea of overlapping sets:

2009 Finiasz and Sendrier: X_1 and X_2 can overlap

2012 Becker, Joux, May and Meurer: can add redundant errors in the overlap



New directions

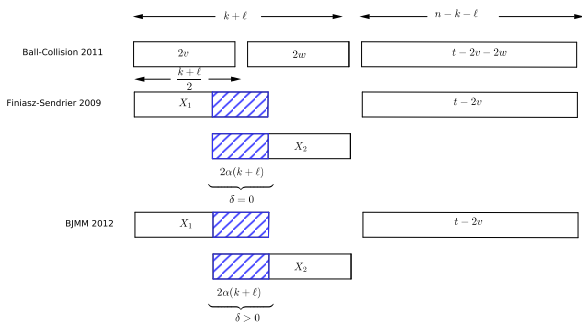
New parameters:

α overlap-ratio

δ amount of redundant errors

2009 Finiasz and Sendrier: $\alpha = 1/2, \delta = 0$

2012 BJMM: $\alpha = 1/2, \delta > 0$



Comparison of Complexities

Let $F(q, R)$ be the exponent of the optimized asymptotic complexity. The asymptotic complexity of half-distance decoding at rate R over \mathbb{F}_q is then given by $q^{F(q,R)n+o(n)}$.

q	q -Stern	q -Stern-MO	q -Ball-collision	q -BJMM-MO
2	0.05563	0.05498	0.055573	0.04730
3	0.05217	0.05242	0.052145	0.04427
4	0.04987	0.05032	0.049846	0.04294
5	0.04815	0.04864	0.048140	0.03955
7	0.04571	0.04614	0.045697	0.03706
8	0.04478	0.04519	0.044770	0.03593
11	0.04266	0.04299	0.042656	0.03335

- Is partitioning into more sets giving us better asymptotic complexities?
- With new code-based cryptographic schemes, e.g. using rank-metric codes, can we adapt these ideas to these metrics?
- Can we use some structure, e.g. of cyclic codes, to improve the ISD algorithms in these cases?

Thank you!