

# Probability II – Lecture notes

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# 1 Basics from Analysis 3 and Probability 1

The goal of this section is to review basic facts from Analysis 3 and Probability 1 that we will use for the rest of the course.

If  $(\Omega, \mathcal{F}, \mathbb{P})$  is a probability space, we define for  $p \in [1, \infty)$ ,

$$L^p = \{X : \Omega \rightarrow \mathbb{R}, \mathcal{F}\text{-measurable}, \mathbb{E}[|X|^p] < \infty\}$$

Up to equivalence classes,  $L^p$  is a Banach space with norm  $\|X\|_{L^p} = \mathbb{E}[|X|^p]^{1/p}$ . We also define

$$\|X\|_{L^\infty} = \inf\{C > 0 : \mathbb{P}[|X| \leq C] = 1\}$$

and

$$L^\infty = \{X : \Omega \rightarrow \mathbb{R}, \mathcal{F}\text{-measurable}, \|X\|_{L^\infty} < \infty\}.$$

Up to equivalence classes,  $L^\infty$  is also a Banach space with norm  $\|X\|_{L^\infty}$ .

The following results will be relevant in this course. If  $(\alpha_k) \in \mathbb{R}$  and  $(A_k) \in \mathcal{F}$  are disjoint, then  $X_n = \sum_{k=1}^n \alpha_k \mathbf{1}_{A_k}$  is called a **simple function**.

**Theorem 1.1** (Density).

- 1) If  $X \geq 0$ , there exists a sequence of simple functions  $X_n \geq 0$  such that  $X_n \nearrow X$  as  $n \rightarrow \infty$ .
- 2) Simple functions are dense in  $L^p$  for any  $p \in [1, \infty]$ .
- 3)  $C_c^\infty(\mathbb{R})$  is dense in  $L^p(\mathbb{R})$  for any  $p \in [1, \infty)$ .

**Proposition 1.2.**

- 1)  $L^q \subset L^p$  for any  $p, q \in [1, \infty]$  with  $p < q$ .
- 2) Hölder's inequality: For any  $p, q \in [1, \infty]$  with  $1/p + 1/q = 1$ ,

$$\mathbb{E}[XY] \leq \|X\|_p \|Y\|_q.$$

- 3) Moreover, it holds  $\|X\|_{L^p} = \sup\{\mathbb{E}[|X|Y] : Y \geq 0, \|Y\|_{L^q} = 1\}$ .

**Remark 1.3.** If  $p \in [1, \infty)$ , the sup in 3) is attained for  $Y = |X|^{p/q}$ . This implies that if  $q > 1$  is given by  $1/p + 1/q = 1$ , then  $L^q$  is dual of  $L^p$ .

Here is another fundamental inequality in probability theory.

**Proposition 1.4.** Jensen's inequality: If  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  is a convex function and  $X \in L^1$ , then

$$\varphi(\mathbb{E}[X]) \leq \mathbb{E}[\varphi(X)].$$

Let us now review the two fundamental results on convergence of independent random variables.

**Theorem 1.5** (Kolmogorov's Law of large numbers). *Let  $(X_n)$  be a sequence of i.i.d. random variables in  $L^1$  with mean  $\mu$ . Then it holds almost surely and in  $L^1$ ,*

$$\lim_{N \rightarrow \infty} \frac{X_1 + \cdots + X_N}{N} = \mu.$$

One particular goal of this course is to give a proof of this result and to generalize it in the case where the random variables  $(X_n)$  are not necessarily independent (see Section ??).

The fluctuations of this sum around its mean are of order  $1/\sqrt{N}$  and asymptotically Gaussian.

**Theorem 1.6** (Central limit theorem). *Let  $(X_n)$  be a sequence of independent random variables in  $L^2$  with  $\mathbb{E}[X_n] = 0$  and  $\mathbb{E}[X_n^2] = \sigma_n^2$ . Let  $\Sigma_N = \sqrt{\sum_{n=1}^N \sigma_n^2}$  and let us suppose that for any  $\epsilon > 0$ ,*

$$\lim_{N \rightarrow \infty} \frac{1}{\Sigma_N^2} \sum_{n=1}^N \mathbb{E}[X_n^2 \mathbf{1}_{|X_n| > \epsilon \Sigma_N}] = 0. \quad (1.1)$$

Then  $\frac{X_1 + \cdots + X_N}{\Sigma_N} \Rightarrow \mathcal{N}_{0,1}$  as  $N \rightarrow \infty$ .

(1.1) is known as the Lindeberg's condition.

*Proof by Lindeberg's replacement strategy.* Let  $f \in C_c^\infty(\mathbb{R})$ . By Taylor's theorem, it holds for any  $\epsilon > 0$  and all  $x, y \in \mathbb{R}$ ,

$$|f(x+y) - f(x) - f'(x)y - f''(x)y^2/2| \leq R_\epsilon(y) := C(\epsilon \mathbf{1}_{|y| \leq \epsilon} + \mathbf{1}_{|y| > \epsilon})y^2, \quad (1.2)$$

where  $C = \|f''\|_\infty + \|f'''\|_\infty/6$  depends only on the test function  $f$ .

Let  $(Z_n)$  be a sequence of independent Gaussian random variables on  $(\Omega, \mathcal{F}, \mathbb{P})$  which is also independent from  $(X_n)$ , with  $Z_n \sim \mathcal{N}_{0, \sigma_n^2}$ . Let us denote for any  $N \in \mathbb{N}$  and  $n \leq N$ ,  $X_{N,n} := X_n/\Sigma_N$  and  $Z_{N,n} := Z_n/\Sigma_N$ . The strategy is to find out the distribution of  $\frac{X_1 + \cdots + X_N}{\Sigma_N} = X_{N,1} + \cdots + X_{N,N}$  by replacing the random variables  $X_{N,k}$  by  $Z_{N,k}$  successively. Let us also denote

$$S_N^{(k)} = Z_{N,1} + \cdots + Z_{N,k} + X_{N,k+1} + \cdots + X_{N,N}, \quad \text{for } k \in \{0, \dots, N\}.$$

In particular, we have

$$S_N^{(0)} = X_{N,1} + \cdots + X_{N,N} = \frac{X_1 + \cdots + X_N}{\Sigma_N} \quad \text{and} \quad S_N^{(N)} = Z_{N,1} + \cdots + Z_{N,N}. \quad (1.3)$$

Fix  $k \in \{1, \dots, N\}$ , by applying (1.2) with  $x = Z_{N,1} + \cdots + Z_{N,k-1} + X_{N,k+1} + \cdots + X_{N,N}$  and  $y = X_{N,k}$ , we obtain

$$|f(S_N^{(k-1)}) - f(x) - f'(x)X_{N,k} - f''(x)X_{N,k}^2/2| \leq R_\epsilon(X_{N,k}).$$

By taking expectations on both sides, this implies that

$$|\mathbb{E}[f(S_N^{(k-1)})] - \mathbb{E}[f(x)] - \mathbb{E}[f''(x)] \mathbb{E}[X_{N,k}^2] / 2| \leq \mathbb{E}[R_\epsilon(X_{N,k})], \quad (1.4)$$

where we used that  $x$  is independent from  $y = X_{N,k}$  and that  $\mathbb{E}[X_{N,k}] = 0$ .

Similarly, with  $x = Z_{N,1} + \dots + Z_{N,k-1} + X_{N,k+1} + \dots + X_{N,N}$  and  $y = Z_{N,k}$ ,

$$|\mathbb{E}[f(S_N^{(k)})] - \mathbb{E}[f(x)] - \mathbb{E}[f''(x)] \mathbb{E}[Z_{N,k}^2] / 2| \leq \mathbb{E}[R_\epsilon(Z_{N,k})]. \quad (1.5)$$

By combining the bounds (1.4)–(1.5) and using the triangle inequality, since  $\mathbb{E}[X_{N,k}^2] = \mathbb{E}[Z_{N,k}^2]$  by construction, we obtain

$$|\mathbb{E}[f(S_N^{(k)})] - \mathbb{E}[f(S_N^{(k-1)})]| \leq \mathbb{E}[R_\epsilon(X_{N,k})] + \mathbb{E}[R_\epsilon(Z_{N,k})].$$

By summing the previous estimates for  $k = 1, \dots, N$  and using that the terms are telescoping, this implies that

$$|\mathbb{E}[f(S_N^{(N)})] - f(S_N^{(0)})| \leq \sum_{k=1}^N |\mathbb{E}[f(S_N^{(k)})] - \mathbb{E}[f(S_N^{(k-1)})]| \leq \sum_{k=1}^N \mathbb{E}[R_\epsilon(X_{N,k})] + \sum_{k=1}^N \mathbb{E}[R_\epsilon(Z_{N,k})]. \quad (1.6)$$

Note that by definitions,  $\sum_{k=1}^N \mathbb{E}[X_{N,k}^2] = 1$  and the error can be controlled by

$$\begin{aligned} \sum_{k=1}^N \mathbb{E}[R_\epsilon(X_{N,k})] &= C\epsilon \sum_{k=1}^N \mathbb{E}[X_{N,k}^2 \mathbf{1}_{|X_{N,k}| \leq \epsilon}] + C \sum_{k=1}^N \mathbb{E}[X_{N,k}^2 \mathbf{1}_{|X_{N,k}| > \epsilon}] \\ &\leq C\epsilon + C \sum_{k=1}^N \mathbb{E}[X_{N,k}^2 \mathbf{1}_{|X_{N,k}| > \epsilon}] \end{aligned}$$

Now, using the condition (1.1), we verify that for any  $\epsilon > 0$ ,

$$\limsup_{N \rightarrow \infty} \sum_{k=1}^N \mathbb{E}[R_\epsilon(X_{N,k})] \leq C\epsilon.$$

We want to prove a similar claim for the Gaussian random variables  $Z_{N,k}$ . This is the goal of the next exercise.

**Exercise 1.1.** 1) Show that the condition (1.1) implies that  $\lim_{N \rightarrow \infty} \max_{n \leq N} \left( \frac{\sigma_n^2}{\sum_{N}^2} \right) = 0$ .

2) Deduce that the sequence  $(Z_n)_{n \geq 1}$  also satisfies Lindeberg's condition (1.1).

3) Show that  $Z_{N,1} + \dots + Z_{N,n} \sim \mathcal{N}_{0,1}$ .

Exactly as above, 2) implies that  $\limsup_{N \rightarrow \infty} \sum_{k=1}^N \mathbb{E}[R_\epsilon(Z_{N,k})] \leq C\epsilon$ . Hence, by (1.6), we conclude that

$$\limsup_{N \rightarrow \infty} |\mathbb{E}[f(S_N^{(N)}) - f(S_N^{(0)})]| \leq 2C\epsilon.$$

Since the parameter  $\epsilon$  is arbitrarily small, this shows that  $\lim_{N \rightarrow \infty} \mathbb{E}[f(S_N^{(N)}) - f(S_N^{(0)})] = 0$ .

To finish the proof, we use (1.3) and note that by 3),  $\mathbb{E}[f(S_N^{(N)})] = \mathbb{E}[f(\mathcal{N}_{0,1})]$ , so we have shown that

$$\lim_{N \rightarrow \infty} \mathbb{E}[f(\frac{X_1 + \dots + X_N}{\Sigma_N})] = \mathbb{E}[f(\mathcal{N}_{0,1})]. \quad (1.7)$$

Since (1.7) holds for any test function  $f \in C_c^\infty(\mathbb{R})$ , we conclude that  $\frac{X_1 + \dots + X_N}{\Sigma_N} \Rightarrow \mathcal{N}_{0,1}$ .  $\square$

## 2 Conditional expectation

### 2.1 $L^2$ theory

$L^2(\Omega, \mathcal{F}, \mathbb{P})$  is a **Hilbert space** with inner product  $X, Y \mapsto \mathbb{E}[XY]$ . The following result from analysis will be relevant for our construction of conditional expectation.

**Theorem 2.1** (Orthogonal Projection). *Let  $\mathcal{H}$  be a Hilbert space and  $\mathcal{L} \subset \mathcal{H}$  be a (closed) subspace. We define  $x \in \mathcal{H} \mapsto d(x, \mathcal{L}) = \inf\{\|x - y\| : y \in \mathcal{L}\}$ . For any  $x \in \mathcal{H}$ , there exists a **unique**  $x_{\mathcal{L}} \in \mathcal{L}$  such that*

$$\|x - x_{\mathcal{L}}\| = d(x, \mathcal{L}).$$

$x_{\mathcal{L}}$  is called **the (orthogonal) projection** of  $x$  on  $\mathcal{L}$  and it is characterized by the following property:  $z \in \mathcal{L}$  satisfies

$$\langle z, y \rangle = \langle x, y \rangle, \quad \forall y \in \mathcal{L}, \quad (2.1)$$

if and only if  $z = x_{\mathcal{L}}$ .

*Proof.* We are going to use the (parallelogram) identity: for any  $y, y' \in \mathcal{H}$ ,

$$\|y - y'\|^2 + \|y + y'\|^2 = 2(\|y\|^2 + \|y'\|^2). \quad (2.2)$$

By definition, there exists a sequence  $y_n \in \mathcal{L}$  such that  $\|y_n - x\| \rightarrow d(x, \mathcal{L})$  as  $n \rightarrow \infty$ . Let us show that  $(y_n)$  is a Cauchy sequence. By (2.2), we obtain

$$\|y_n - y_m\|^2 + \|2x - y_n - y_m\|^2 = 2\|x - y_n\|^2 + 2\|x - y_m\|^2.$$

Using that  $\|2x - y_n - y_m\| = 2\|x - \frac{y_n + y_m}{2}\| \geq 2d(x, \mathcal{L})$ , we obtain

$$\|y_n - y_m\|^2 \leq \epsilon_n + \epsilon_m \quad \text{where} \quad \epsilon_n = 2\|x - y_n\|^2 - 2d(x, \mathcal{L})^2.$$

As  $\epsilon_n \rightarrow 0$  as  $n \rightarrow \infty$ , this shows that  $(y_n)$  is a Cauchy sequence and, as  $\mathcal{H}$  is complete,  $y_n \rightarrow x_{\mathcal{L}}$  in  $\mathcal{H}$ . Since  $\mathcal{L}$  is closed, we also have  $x_{\mathcal{L}} \in \mathcal{L}$  and by continuity,

$$\|x_{\mathcal{L}} - x\| = \lim_{n \rightarrow \infty} \|y_n - x\| = d(x, \mathcal{L}).$$

The Cauchy property also implies that this limit  $x_{\mathcal{L}} \in \mathcal{L}$  is unique.

To prove that the projection  $x_{\mathcal{L}}$  satisfies (2.1), fix  $y \in \mathcal{L}$  and consider the map:

$$\lambda \in \mathbb{R} \mapsto \|x - x_{\mathcal{L}} + \lambda y\|^2 = \|x - x_{\mathcal{L}}\|^2 + 2\lambda \langle x - x_{\mathcal{L}}, y \rangle + \lambda^2 \|y\|^2.$$

This map is a polynomial of degree 2 and (by definition of  $x_{\mathcal{L}}$ ) its unique minimum is attained at  $\lambda = 0$ . Hence, we have

$$\left. \frac{d}{d\lambda} \|x - x_{\mathcal{L}} + \lambda y\|^2 \right|_{\lambda=0} = 2\langle x - x_{\mathcal{L}}, y \rangle = 0.$$

Since it is true for any  $y \in \mathcal{L}$ , this shows that  $(x - x_{\mathcal{L}}) \in \mathcal{L}^{\perp}$  (equivalently,  $x_{\mathcal{L}}$  satisfies (2.1)). To conclude the proof, it remains to show that the equation (2.1) has a unique solution. If  $z \in \mathcal{L}$  satisfies (2.1), then for any  $y \in \mathcal{L}$ ,

$$\|x - y\|^2 = \|x - z\|^2 + \|z - y\|^2 + 2 \underbrace{\langle x - z, y - z \rangle}_{=0 \text{ since } (y-z) \in \mathcal{L}} \geq \|x - z\|^2.$$

Now, taking the infimum over all  $y \in \mathcal{L}$  on the LHS, this shows that

$$d(x, \mathcal{L}) = \|x - z\|.$$

This computation implies that  $z = x_{\mathcal{L}}$  is the (orthogonal) projection of  $x$  on  $\mathcal{L}$ .  $\square$

**Corollary 2.2.** *For any (closed) subspace  $\mathcal{L} \subset \mathcal{H}$ , the map  $\pi_{\mathcal{L}} : x \in \mathcal{H} \mapsto x_{\mathcal{L}} \in \mathcal{L}$  is linear.*

*Proof.* For  $\alpha \in \mathbb{R}$  and  $x, x' \in \mathcal{H}$ , we have to show that  $\pi_{\mathcal{L}}(\alpha x + x') = \alpha x_{\mathcal{L}} + x'_{\mathcal{L}}$ . By Theorem 2.1, it suffices to check that this vector satisfies (2.1). This follows directly by bi-linearity of the inner product on  $\mathcal{H}$ .  $\square$

**Remark 2.3.** *The linear map  $\pi_{\mathcal{L}}$  is an orthogonal projection in the sense that  $\pi_{\mathcal{L}}|_{\mathcal{L}} = \text{I}$  and that  $\text{Ker}(\pi_{\mathcal{L}}) = 0$ . Moreover, it is immediate to check that if  $\mathcal{L}' \subset \mathcal{L}$  is a (closed) subspace, then  $\pi_{\mathcal{L}'}\pi_{\mathcal{L}} = \pi_{\mathcal{L}'}$  (this is the ‘tower property’).*

Let  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra. By definition,  $\mathcal{L} = L^2(\Omega, \mathcal{A}, \mathbb{P})$  is a closed linear subspace of  $\mathcal{H} = L^2(\Omega, \mathcal{F}, \mathbb{P})$  and we denote by  $\mathbb{E}[\cdot|\mathcal{A}]$  the (linear) projection  $\mathcal{H} \rightarrow \mathcal{L}$ .

Then, for any  $X \in L^2(\Omega, \mathcal{F}, \mathbb{P})$ , this defines a random variable  $\mathbb{E}[X|\mathcal{A}] \in L^2(\Omega, \mathcal{A}, \mathbb{P})$ . Moreover by Theorem 2.1, an  $\mathcal{A}$ -measurable random variable  $Z$  satisfies

$$\mathbb{E}[ZY] = \mathbb{E}[XY], \quad \forall Y \in L^2(\Omega, \mathcal{A}, \mathbb{P}), \quad (2.3)$$

if and only if  $Z = \mathbb{E}[X|\mathcal{A}]$ .

The random variable  $\mathbb{E}[X|\mathcal{A}]$  is called the **conditional expectation of  $X$  knowing  $\mathcal{A}$** . The conditional expectation has the following basic properties.

**Proposition 2.4.** *The map  $\mathbb{E}[\cdot|\mathcal{A}]$  is linear and positive on  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  and it satisfies*

$$\|\mathbb{E}[X|\mathcal{A}]\|_{L^2} \leq \|X\|_{L^2}, \quad \forall X \in L^2(\Omega, \mathcal{F}, \mathbb{P}) \quad (2.4)$$

*Proof.* Linearity and (2.4) follow immediately by definition (see Corollary 2.2). Suppose that  $X \geq 0$  with  $X \in L^2(\Omega, \mathcal{F}, \mathbb{P})$ . Since the event  $A = \{\mathbb{E}[X|\mathcal{A}] \leq 0\} \in \mathcal{A}$ , on the one-hand by (2.3), we have

$$\mathbb{E}[\mathbb{E}[X|\mathcal{A}]\mathbf{1}_A] \geq 0.$$

On the other-hand since  $\mathbb{E}[X|\mathcal{A}]\mathbf{1}_A \leq 0$ , we conclude that  $\mathbb{E}[X|\mathcal{A}]\mathbf{1}_{\{\mathbb{E}[X|\mathcal{A}] \leq 0\}} = 0$ . This shows that the random variable  $\mathbb{E}[X|\mathcal{A}]$  is non-negative (hence, the map  $\mathbb{E}[\cdot|\mathcal{A}]$  is positive).  $\square$

The random variable  $\mathbb{E}[X|\mathcal{A}]$  has the following interpretation: it is the best approximation of  $X$  in the space of  $\mathcal{A}$ -measurable functions for the mean-square distance in the sense that  $\mathbb{E}[X|\mathcal{A}]$  is the unique minimizer of  $\|Z - X\|_{L^2}$  over all  $Z \in L^2(\Omega, \mathcal{A}, \mathbb{P})$ .

## 2.2 General theory

In this section, we generalize the concept of conditional expectation in two cases: *i*)  $X \geq 0$  and *ii*)  $X \in L^1$ . These generalizations rely on Proposition 2.4 and two preliminary Lemmas.

**Lemma 2.5.** *If  $X, Z \geq 0$  are  $\mathcal{F}$ -measurable and  $\mathbb{E}[X\mathbf{1}_A] = \mathbb{E}[Z\mathbf{1}_A]$  for all  $A \in \mathcal{F}$ , then  $X = Z$  a.s..*

*Proof.* For any  $\epsilon > 0$  and  $t \geq 0$ , the events  $A_{\epsilon,t} = \{X \geq t + \epsilon, t \geq Z\} \in \mathcal{A}$ . By assumption,

$$\mathbb{E}[Z\mathbf{1}_{A_{\epsilon,t}}] \leq t\mathbb{P}[A_{\epsilon,t}] \quad \text{and} \quad \mathbb{E}[X\mathbf{1}_{A_{\epsilon,t}}] > t\mathbb{P}[A_{\epsilon,t}].$$

This implies that  $\mathbb{P}[A_{\epsilon,t}] = 0$  for any  $t \in \mathbb{Q}_+$ . Moreover, by monotone convergence, for any  $t \in \mathbb{Q}_+$ ,

$$\mathbb{P}[X \geq t \geq Z] = \lim_{\epsilon \rightarrow 0} \mathbb{P}[A_{\epsilon,t}] = 0.$$

Now, by density,  $\mathbb{P}[X \geq Z] = \bigcup_{t \in \mathbb{Q}_+} \mathbb{P}[X \geq t \geq Z] = 0$ . By symmetry, we also have  $\mathbb{P}[X \leq Z] = 0$  and we conclude that  $X = Z$ .  $\square$

**Lemma 2.6.** *If  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$  and  $\mathbb{E}[X\mathbf{1}_A] = 0$  for all  $A \in \mathcal{F}$ , then  $X = 0$ .*

*Proof.* The events  $A_{\pm} = \{X \in \mathbb{R}_{\pm}\} \in \mathcal{F}$ , so by assumptions:  $\mathbb{E}[X\mathbf{1}_{A_{\pm}}] = 0$ . This implies that the random variables  $\pm X\mathbf{1}_{A_{\pm}} \geq 0$  have mean-zero, so that  $X\mathbf{1}_{A_{\pm}} = 0$ .  $\square$

Let us now extend the definition of  $\mathbb{E}[X|\mathcal{A}]$  to any positive random variable  $X$ .

**Theorem 2.7.** *Suppose that  $X \geq 0$  is  $\mathcal{F}$ -measurable and  $\mathcal{A} \subset \mathcal{F}$  is a  $\sigma$ -algebra. There exists a unique random variable  $Z \geq 0$  which is  $\mathcal{A}$ -measurable such that*

$$\mathbb{E}[ZW] = \mathbb{E}[XW], \quad \forall W \geq 0, \mathcal{A}\text{-measurable.} \quad (2.5)$$

We denote  $Z = \mathbb{E}[X|\mathcal{A}]$ .

*Proof.* The random variables  $X_n = X \wedge n \in L^2$ , so we can define  $Z_n = \mathbb{E}[X_n|\mathcal{A}] \geq 0$  (see Proposition 2.4). Moreover, since  $(X_n)$  is non-decreasing, it follows that  $(Z_n)$  is also non-decreasing. Hence,  $Z_{\infty} = \lim_{n \rightarrow \infty} Z_n$  exists with  $Z_{\infty} \in [0, \infty]$  and for any  $W \geq 0$  ( $\mathcal{F}$ -measurable),

$$\lim_{n \rightarrow \infty} \mathbb{E}[Z_n W] = \mathbb{E}[Z_{\infty} W]. \quad (2.6)$$

Now for any  $Y \in L^2(\Omega, \mathcal{A}, \mathbb{P})$ ,  $\mathbb{E}[Z_n Y] = \mathbb{E}[X_n Y]$  by applying (2.3), so that by (2.6),

$$\mathbb{E}[XY] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n Y] = \mathbb{E}[Z_{\infty} Y].$$

In particular, this holds for all positive simple function  $Y$  which are  $\mathcal{A}$ -measurable and by Theorem 1.1.1), this shows that  $Z_{\infty}$  satisfies (2.5). Uniqueness of this solution follows directly from Lemma 2.5.  $\square$

Similarly, we can also extend the definition of  $\mathbb{E}[X|\mathcal{A}]$  to  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$ .

**Theorem 2.8.** *Suppose that  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$  and  $\mathcal{A} \subset \mathcal{F}$  is a  $\sigma$ -algebra. There exists a unique random variable  $Z \in L^1(\Omega, \mathcal{A}, \mathbb{P})$  such that*

$$\mathbb{E}[ZW] = \mathbb{E}[XW], \quad \forall W \in L^{\infty}(\Omega, \mathcal{A}, \mathbb{P}). \quad (2.7)$$

We denote  $Z = \mathbb{E}[X|\mathcal{A}]$  and it satisfies  $\|\mathbb{E}[X|\mathcal{A}]\|_{L^1} \leq \|X\|_{L^1}$ .



*Proof.* We decompose  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$  as

$$X = X_+ - X_-, \quad \text{where } X_{\pm} = |X| \mathbf{1}_{X \in \mathbb{R}_{\pm}}. \quad (2.8)$$

We apply Theorem 2.7 and set  $Z_{\pm} = \mathbb{E}[X_{\pm} | \mathcal{A}] \geq 0$ . Note that since  $X_{\pm} \in L^1$ , we also have  $Z_{\pm} \in L^1$  by (2.5) with  $W = 1$ . Let  $Z := Z_+ - Z_-$ . By construction,  $Z \in L^1(\Omega, \mathcal{A}, \mathbb{P})$  and by (2.5), it satisfies

$$\mathbb{E}[ZW] = \mathbb{E}[XW], \quad \forall W \in L^\infty(\Omega, \mathcal{A}, \mathbb{P}), W \geq 0.$$

This implies that  $Z$  satisfies (2.7) by decomposing  $W$  according to (2.8) and using linearity of  $\mathbb{E}[\cdot]$ . Uniqueness of this solution follows directly from Lemma 2.6. It just remains to verify that  $\|Z\|_{L^1} \leq \|X\|_{L^1}$ . If we take  $W = \text{sgn}(Z)$  in (2.8), since  $\|\text{sgn}(Z)\|_{L^\infty} \leq 1$  we deduce from Hölder's inequality that

$$\|Z\|_{L^1} = \mathbb{E}[Z \text{sgn}(Z)] = \mathbb{E}[X \text{sgn}(Z)] \leq \|X\|_{L^1}. \quad \square$$

We are now ready to formalize our definition of conditional expectation.

**Definition 2.1.** Let  $X \geq 0$  or  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$  and  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra. We define  $\mathbb{E}[X | \mathcal{A}]$  to be the unique random variable  $Z$  which is  $\mathcal{A}$ -measurable and satisfies

$$\mathbb{E}[Z \mathbf{1}_A] = \mathbb{E}[X \mathbf{1}_A], \quad \forall A \in \mathcal{A}. \quad (2.9)$$

$\mathbb{E}[X | \mathcal{A}]$  is called the **conditional expectation of  $X$  knowing  $\mathcal{A}$**  and it satisfies:

*i)*  $\mathbb{E}[X | \mathcal{A}] \geq 0$  if  $X \geq 0$ . *ii)*  $\mathbb{E}[X | \mathcal{A}] \in L^1$  if  $X \in L^1$ .

This definition is consistent with both Theorem 2.7 and Theorem 2.8. In particular by a standard *density argument* (using Theorem 1.1): *i)* if  $X \geq 0$ , the condition (2.9) is equivalent to (2.5). *ii)* if  $X \in L^1$ , the condition (2.9) is equivalent to (2.7).

**Remark 2.9.** • The **fundamental property** (2.9) characterizes  $\mathbb{E}[X | \mathcal{A}]$ . It means that to verify whether an  $\mathcal{A}$ -measurable random variable  $Z$  is  $\mathbb{E}[X | \mathcal{A}]$ , it suffices to check that it satisfies (2.9). In particular, if  $X$  is  $\mathcal{A}$ -measurable, then  $\mathbb{E}[X | \mathcal{A}] = X$ .

- By the **monotone class Theorem**, it suffices to check that (2.9) is satisfied for all  $A \in \Pi$  where  $\Pi$  is any  $\pi$ -system so that  $\mathcal{A} = \sigma(\Pi)$ .
- Observe that  $\mathbb{E}[\cdot] = \mathbb{E}[\cdot | \mathcal{A}]$  where  $\mathcal{A} = \{\emptyset, \Omega\}$  is the trivial  $\sigma$ -algebra.

**Notation 2.2.** • For any  $B \in \mathcal{F}$ , we denote by  $\mathbb{P}[B | \mathcal{A}] = \mathbb{E}[\mathbf{1}_B | \mathcal{A}]$ .

- For any random variable  $Y$  on  $(\Omega, \mathcal{F}, \mathbb{P})$ , we denote  $\mathbb{E}[\cdot | Y] = \mathbb{E}[\cdot | \sigma(Y)]$ .

## 2.3 Properties of conditional expectation

The goal of this section is to report on how to compute conditional expectations, that is to give the basic properties of  $\mathbb{E}[\cdot|\mathcal{A}]$ . This first proposition follows immediately from the construction in Section 2.2 – see also Corollary 2.4.

**Proposition 2.10.** *The map  $\mathbb{E}[\cdot|\mathcal{A}]$  is linear and positive on  $L^1(\Omega, \mathcal{F}, \mathbb{P})$ .*

As a consequence of Proposition 2.10, one has similar calculus rules for  $\mathbb{E}[\cdot|\mathcal{A}]$  as for the usual expectation  $\mathbb{E}[\cdot]$ , except that the output is a **random variable**.

**Proposition 2.11.** *Let  $(X_n)$  be random variables on  $(\Omega, \mathcal{F}, \mathbb{P})$  and  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra.*

1. (Monotone convergence) *If there exists a constant  $C \geq 0$  such that  $X_n \geq -C$  and  $X_n \nearrow X_\infty$  a.s., then as  $n \rightarrow \infty$ ,*

$$\mathbb{E}[X_n|\mathcal{A}] \nearrow \mathbb{E}[X_\infty|\mathcal{A}] \quad \text{a.s.}$$

2. (Fatou's lemma) *If there exists a constant  $C \geq 0$  such that  $X_n \geq -C$ , then a.s.,*

$$\liminf_{n \rightarrow \infty} \mathbb{E}[X_n|\mathcal{A}] \geq \mathbb{E}[\liminf_{n \rightarrow \infty} X_n|\mathcal{A}].$$

3. *If  $X_n \rightarrow X_\infty$  in  $L^1$ , then  $\mathbb{E}[X_n|\mathcal{A}] \rightarrow \mathbb{E}[X_\infty|\mathcal{A}]$  in  $L^1$ .*

Proposition 2.11.3. is a direct consequence from the last bound in Theorem 2.8. This statement replaces the usual *dominated convergence theorem*.

*Proof.* 1. Since  $X_n \geq -C$ , its conditional expectation is well defined in the sense of Theorem 2.7. By positivity, the sequence  $\mathbb{E}[X_n|\mathcal{A}]$  is non-decreasing so it has limit  $Z \geq -C$  which is  $\mathcal{A}$ -measurable. To check that  $Z = \mathbb{E}[X_\infty|\mathcal{A}]$  it suffices to verify it satisfies the condition (2.9): for any  $A \in \mathcal{A}$ ,

$$\mathbb{E}[Z\mathbf{1}_A] = \lim_{n \rightarrow \infty} \mathbb{E}[\mathbb{E}[X_n|\mathcal{A}]\mathbf{1}_A] = \lim_{n \rightarrow \infty} \mathbb{E}[X_n\mathbf{1}_A] = \mathbb{E}[X_\infty\mathbf{1}_A],$$

where both limits exist by the usual monotone convergence theorem.

2. We use the usual argument, by positivity, it holds for any  $n \in \mathbb{N}$ ,

$$\mathbb{E}\left[\inf_{k \geq n} X_k|\mathcal{A}\right] \leq \inf_{k \geq n} \mathbb{E}[X_k|\mathcal{A}].$$

Using 1., we have  $\lim_{n \rightarrow \infty} \mathbb{E}\left[\inf_{k \geq n} X_k|\mathcal{A}\right] = \mathbb{E}\left[\liminf_{n \rightarrow \infty} X_n|\mathcal{A}\right]$  which yields the claim.  $\square$

We also have the following version of Jensen's inequality which is important.

**Lemma 2.12** (Jensen's inequality). *Let  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra,  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  be a convex function and  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$ , then a.s.,*

$$\varphi(\mathbb{E}[X|\mathcal{A}]) \leq \mathbb{E}[\varphi(X)|\mathcal{A}].$$

*Proof.* We rely on the fact that a function  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  is convex if and only if  $\varphi(x) = \sup_{n \geq 1}(\alpha_n x + \beta_n)$  for two sequences  $\alpha_n, \beta_n \in \mathbb{R}$ . Then, by Proposition 2.10,

$$\mathbb{E}[\varphi(X)|\mathcal{A}] \geq \sup_{n \geq 1}(\mathbb{E}[\alpha_n X + \beta_n|\mathcal{A}]) = \sup_{n \geq 1}(\alpha_n \mathbb{E}[X|\mathcal{A}] + \beta_n).$$

Note that we do not exclude the possibility that  $\mathbb{E}[\varphi(X)|\mathcal{A}] = +\infty$  here and we used that  $X \in L^1$  so that the RHS is well-defined with the trivial observation that  $\mathbb{E}[1|\mathcal{A}] = 1$ . By definition, the RHS equals to  $\varphi(\mathbb{E}[X|\mathcal{A}]) \in \mathbb{R}$ .  $\square$

**Remark 2.13.** *The inequality of Lemma 2.12 also holds if we assume instead that  $\varphi : \mathbb{R}_+ \rightarrow \mathbb{R}$  is convex and  $X \geq 0$ .*

We obtain the following inequalities as a direct consequence of Lemma 2.12.

**Proposition 2.14** (Norm's estimates). *Let  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra. For any  $p \in [1, \infty]$  and for all  $X \in L^p(\Omega, \mathcal{F}, \mathbb{P})$ ,*

$$\|\mathbb{E}[X|\mathcal{A}]\|_{L^p} \leq \|X\|_{L^p}.$$

*Proof.* Since the function  $x \in \mathbb{R} \mapsto |x|^p$  is convex for any  $p \in [1, \infty)$ , by Jensen's inequality,

$$|\mathbb{E}[X|\mathcal{A}]|^p \leq \mathbb{E}[|X|^p|\mathcal{A}]. \quad (2.10)$$

Taking expectation and using that  $\mathbb{E}[\mathbb{E}[|X|^p|\mathcal{A}]] = \mathbb{E}[|X|^p]$ , this implies the claim.

For  $p = \infty$ , we use Proposition 1.2.3) and write

$$\|\mathbb{E}[X|\mathcal{A}]\|_{L^\infty} = \sup\{\mathbb{E}[\mathbb{E}[X|\mathcal{A}]|Y] : Y \geq 0, Y \text{ is } \mathcal{A}\text{-measurable, } \mathbb{E}[Y] = 1\}.$$

Note that since  $\mathbb{E}[X|\mathcal{A}]$  is  $\mathcal{A}$ -measurable, we can take the supremum only over function  $Y$  which are also  $\mathcal{A}$ -measurable. Now, using (2.10) with  $p = 1$ , it holds for any  $Y \geq 0$ ,  $\mathcal{A}$ -measurable,

$$\mathbb{E}[\mathbb{E}[X|\mathcal{A}]|Y] \leq \mathbb{E}[\mathbb{E}[|X|\mathcal{A}]|Y] = \mathbb{E}[|X|Y] \leq \|X\|_\infty \mathbb{E}[Y].$$

This inequality implies that  $\|\mathbb{E}[X|\mathcal{A}]\|_{L^\infty} \leq \|X\|_\infty$ .  $\square$

Let us now give the three crucial properties which are specific to conditional expectation.

**Proposition 2.15** (Important properties). *Let  $X \geq 0$  or  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$ .*

1. (Tower property) *If  $\mathcal{B} \subset \mathcal{A} \subset \mathcal{F}$  are  $\sigma$ -algebra, then*

$$\mathbb{E}[\mathbb{E}[X|\mathcal{A}]|\mathcal{B}] = \mathbb{E}[X|\mathcal{B}].$$

2. (Taking out what is known) *If  $Y$  is  $\mathcal{A}$ -measurable and  $Y \geq 0$  or  $XY \in L^1$ , then*

$$\mathbb{E}[XY|\mathcal{A}] = Y\mathbb{E}[X|\mathcal{A}].$$

3. *If  $\sigma(X)$  is independent from  $\mathcal{A}$ , then  $\mathbb{E}[X|\mathcal{A}] = \mathbb{E}[X]$ .*

*Proof.* For 1., 2. and 3., it suffices to check that the fundamental property (2.9) is satisfied.  $\square$

Our last property is a generalization of Proposition 2.15.3.

**Proposition 2.16.** *Let  $X, Y$  be two random variables such that  $Y$  is  $\mathcal{A}$ -measurable and  $\sigma(X)$  is independent from  $\mathcal{A}$ . Let  $h$  be a real-valued function such that  $h \geq 0$  or  $h(X, Y) \in L^1$ . Then*

$$\mathbb{E}[h(X, Y)|\mathcal{A}] = g(Y) \quad \text{where} \quad g(y) = \int h(x, y)\mathbf{P}_X(dx).$$

*Proof.* In class, we give an easier proof in case  $\mathcal{A} = \sigma(Y)$ . We now give a general argument. Let  $Z \in L^\infty(\Omega, \mathcal{A}, \mathbb{P})$  with  $Z \geq 0$ . Using that  $\sigma(X)$  and  $\mathcal{A}$ , the law of the vector  $(X, Y, Z)$  factorizes:  $\mathbf{P}_{(X, Y, Z)} = \mathbf{P}_X \otimes \mathbf{P}_{(Y, Z)}$ . By Fubini's theorem and the definition of  $g$ , this implies that

$$\mathbb{E}[h(X, Y)Z] = \iint h(x, y)z\mathbf{P}_X(dx)\mathbf{P}_{(Y, Z)}(dy, dz) = \int g(y)z\mathbf{P}_{(Y, Z)}(dy, dz) = \mathbb{E}[g(Y)Z].$$

Note that  $g$  is measurable and applying Fubini's theorem is justified in both case  $h \geq 0$  or  $h \in L^1(\mathbf{P}_X \otimes \mathbf{P}_Y)$ . By (2.9), this computation shows that  $\mathbb{E}[h(X, Y)|\mathcal{A}] = g(Y)$ .  $\square$

**Proposition 2.17.** *Let  $X \in L^1$  (or  $X \geq 0$ ) and  $\mathcal{A}, \mathcal{B} \subset \mathcal{F}$  be two  $\sigma$ -algebras so that  $\mathcal{B}$  is independent of  $\sigma(X) \vee \mathcal{A}$ . Then  $\mathbb{E}[X|\mathcal{A}]$  is also independent from  $\mathcal{B}$  and*

$$\mathbb{E}[X|\mathcal{A} \vee \mathcal{B}] = \mathbb{E}[X|\mathcal{A}].$$

*Proof.* See Exercise  $\square$

## 2.4 Explicit cases

### 2.4.1 Discrete setting

Let us suppose that  $\mathcal{A} = \sigma(\Pi)$  is generated by a (countable) partition  $\Pi = \{A_n\}$  of  $\Omega$  (that is the events  $A_n$  are disjoint with  $\mathbb{P}[A_n] > 0$  and  $\Omega = \bigcup_n A_n$ ). In this case, it holds for any random variable  $X \geq 0$  or  $X \in L^1(\Omega, \mathcal{F}, \mathbb{P})$ ,

$$\mathbb{E}[X|\mathcal{A}] = \sum_n \mathbf{1}_{A_n} \mathbb{E}[X|A_n], \quad \mathbb{E}[X|A_n] = \frac{\mathbb{E}[X\mathbf{1}_{A_n}]}{\mathbb{P}[A_n]}. \quad (2.11)$$

Note that since the events  $A_n$  are disjoint, for every  $\omega \in \Omega$ , the sum on the RHS of (2.11) contains at most one non-zero term. This explicit representation is particularly useful when  $\mathcal{A} = \sigma(N)$  for a discrete random variable  $N$ .

### 2.4.2 Random variables with a density

Here, we assume that  $(X, Y)$  is a random vector with a density. It means that its law has the form  $\mathbf{P}_{(X,Y)}(dx, dy) = f_{(X,Y)}(x, y)dx dy$  where  $f_{(X,Y)} \in L^1$  and  $f_{(X,Y)} \geq 0$ .

Then  $Y$  also has a density which is given by  $f_Y(y) = \int f_{(X,Y)}(x, y)dx$ .

Let us define a new function  $q \geq 0$  by

$$q(x, y) = \mathbf{1}_{\{f_Y(y) > 0\}} \frac{f_{(X,Y)}(x, y)}{f_Y(y)}.$$

**Proposition 2.18.** *Under the above assumptions, for any function  $h \geq 0$  or  $h \in L^1$ , one has*

$$\mathbb{E}[h(X)|Y] = \int h(x)q(x, Y)dx.$$

*Proof.* Let  $S = \{f_Y(y) > 0\}$  and note that the event  $\{Y \in S\}$  has probability 1. Indeed, we have  $\mathbb{P}[Y \notin S] = \int_{\{f_Y(y)=0\}} f_Y(y)dy = 0$ . Moreover, by definition of  $q$ , it holds for any Borel set  $B$ ,

$$\begin{aligned} \mathbb{E}\left[\mathbf{1}_{Y \in B} \int h(x)q(x, Y)dx\right] &= \iint h(x)\mathbf{1}_{y \in B}q(x, y)f_Y(y)dy \\ &= \iint h(x)\mathbf{1}_{y \in B, y \in S}f_{(X,Y)}(x, y)dx dy \\ &= \mathbb{E}[h(X)\mathbf{1}_{Y \in B, Y \in S}]. \end{aligned}$$

By (2.9), since  $\sigma(Y) = \{Y \in B : B \text{ is a Borel set}\}$  and  $\mathbf{1}_{Y \in S} = 1$  a.s., this proves the claim.  $\square$

### 2.4.3 Gaussian vectors

**Definition 2.3.**  $X = (X_1, \dots, X_n)$  is a **Gaussian vector** on  $L^2(\Omega, \mathcal{F}, \mathbb{P})$  if for any  $a \in \mathbb{R}^n$ ,  $\langle X, a \rangle$  is a real-valued Gaussian variable. We define the mean and **covariance matrix** of  $X$  by

$$\mu_i = \mathbb{E}[X_i], \quad \Sigma_{ij} = \mathbb{E}[(X_i - \mu_i)(X_j - \mu_j)], \quad \text{for } i, j \in \{1, \dots, n\}.$$

We denote the law of the vector  $X$  by  $\mathbf{P}_X = \mathcal{N}_{(\mu, \Sigma)}$ . Then, for any  $a \in \mathbb{R}^n$ ,

$$\mathbf{E}_X[e^{i\langle X, a \rangle}] = e^{i\langle \mu, a \rangle - \langle a, \Sigma a \rangle / 2}.$$

**Lemma 2.19.** Let  $X = (X_1, \dots, X_n)$  be a Gaussian vector with law  $\mathcal{N}_{(0, \Sigma)}$ .

- 1) The random variables  $(X_1, \dots, X_n)$  are independent if and only if the matrix  $\Sigma$  is diagonal.
- 2) There exists a (fixed) lower-triangular matrix  $L$  and a Gaussian vector  $Z \sim \mathcal{N}_{(0, I)}$  so that  $X = LZ$ .

*Proof.* See exercises □

**Proposition 2.20.** Let  $(Y_1, \dots, Y_n, X)$  be a Gaussian vector with law  $\mathcal{N}_{(0, \Sigma)}$  and let  $\mathcal{A} = \sigma(Y_1, \dots, Y_n)$ . There exists a (fixed)  $\lambda \in \mathbb{R}^n$  so that  $Z = \mathbb{E}[X|\mathcal{A}] = \langle \lambda, Y \rangle$ . Moreover, for any function  $f : \mathbb{R} \times \mathbb{R}^n \rightarrow \mathbb{R}_+$ ,

$$\mathbb{E}[f(X, Y)|\mathcal{A}] = \int f(Z + w, Y) \mathbf{P}_{\mathcal{N}(0, \sigma^2)}(dw) = \int f(Z + w, Y) \frac{e^{-w^2/2\sigma^2}}{\sqrt{2\pi}\sigma} dw,$$

where  $\sigma = \|X - Z\|_{L^2} \in \mathbb{R}_+$ .

*Proof.* We use a similar idea as in the proof of Lemma 2.19. Let  $Z = \langle \lambda, Y \rangle$  be the  $L^2$ -projection of  $X$  on  $\text{span}(Y)$ . By Theorem 2.1, we have

$$\mathbb{E}[(X - Z)Y_k] = 0 \quad \text{for all } k \in \{1, \dots, n\}.$$

Since  $(X - Z, Y_1, \dots, Y_n)$  is a Gaussian vector, this implies that  $\sigma(Z - X)$  is independent from  $\mathcal{A}$ . Consequently, we can apply Proposition 2.16 by writing  $f(X, Y) = h(X - Z, Y)$ . Then as  $(X - Z)$  is a centered Gaussian, we obtain  $\mathbb{E}[f(X, Y)|\mathcal{A}] = g(Y)$  where

$$g(y) = \int h(w, y) \mathbf{P}_{(X-Z)}(dw) = \int f(Z + w, y) \mathbf{P}_{\mathcal{N}(0, \sigma^2)}(dw),$$

where  $\sigma = \|X - Z\|_{L^2} \in \mathbb{R}_+$  is the appropriate standard deviation. Moreover, if we apply this result with  $f(x, y) = x$  (this function is in  $L^1(\mathbf{P}_{\mathcal{N}(0, \sigma^2)})$ ), we get  $\mathbb{E}[X|\mathcal{A}] = Z = \langle \lambda, Y \rangle$ . □

## 2.5 Alternative construction: $L^1$ theory

This construction relies on the Radon–Nikodym Theorem that we now review.

**Definition 2.4.** Let  $\mu, \eta$  be two measures on  $(\Omega, \mathcal{F})$ . We say that  $\mu$  is absolutely continuous with respect to  $\eta$  if

$$\mu(A) = 0 \quad \forall A \in \{O \in \mathcal{F} : \eta(O) = 0\}.$$

Then, we write  $\mu \ll \eta$ .

**Theorem 2.21** (Radon–Nikodym). *Let  $\mu, \eta$  be two  $\sigma$ -finite measures on  $(\Omega, \mathcal{F})$ . Then,  $\mu \ll \eta$  if and only if there exists a (unique) function<sup>1</sup>  $f : \Omega \rightarrow \mathbb{R}_+$  so that*

$$\mu(A) = \int_A f d\eta.$$

$f$  is called the **density** of  $\mu$  with respect to  $\eta$  and it is usually denoted by  $f = \frac{d\mu}{d\eta}$ .

*Proof.* We admit this result for now. □

Let  $0 \leq X < \infty$  be a  $\mathcal{F}$ -measurable random variable and  $\mathcal{A} \subset \mathcal{F}$  be a  $\sigma$ -algebra. It is straightforward to check that the set function  $A \in \mathcal{A} \mapsto \mathbb{E}[X\mathbf{1}_A]$  is a  $\sigma$ -finite measure which is absolutely continuous with respect to  $\mathbb{P}$  on  $(\Omega, \mathcal{A})$ . Therefore, by Theorem 2.21, it admits a density that we denote by  $\mathbb{E}[X|\mathcal{A}]$ .

By definition,  $\mathbb{E}[X|\mathcal{A}] \geq 0$  and it is the unique  $\mathcal{A}$ -measurable random variable which satisfies

$$\mathbb{E}[X\mathbf{1}_A] = \mathbb{E}[\mathbb{E}[X|\mathcal{A}]\mathbf{1}_A], \quad \forall A \in \mathcal{A}.$$

This gives an alternative proof of Theorem 2.7.

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<sup>1</sup> $f$  is uniquely defined as an equivalent class of measurable maps on  $(\Omega, \mathcal{F}, \eta)$ .

### 3 Discrete time martingale

We consider the probability space  $(\Omega, \mathcal{F}_\infty, \mathbb{P})$ . The interest of martingale in probability theory lie in that the martingale property is generally easy to verify and there are stopping theorems and general convergence results;

#### 3.1 Definitions

**Definition 3.1.** • A **filtration** is a sequence of  $\sigma$ -algebras  $\mathcal{F} = (\mathcal{F}_n)_{n=0}^\infty$  such that

$$\mathcal{F}_0 \subset \mathcal{F}_1 \subset \dots \subset \mathcal{F}_\infty.$$

• A sequence of random variables  $X = (X_n)_{n=0}^\infty$  is called **adapted to  $\mathcal{F}$**  if

$$X_n \text{ is } \mathcal{F}_n\text{-measurable for any } n \in \mathbb{N}_0.$$

• A sequence of random variables  $X = (X_n)_{n=1}^\infty$  is called **predictable (with respect to  $\mathcal{F}$ )** if

$$X_n \text{ is } \mathcal{F}_{n-1}\text{-measurable for any } n \in \mathbb{N}.$$

•  $X$  is called a **random process** if  $X_n \in L^1(\Omega, \mathcal{F}_n, \mathbb{P})$  for any  $n \in \mathbb{N}$ .

**Definition 3.2.** If  $X = (X_n)_{n=0}^\infty$  is a sequence of random variables, we define its filtration

$$\mathcal{F}^X = (\mathcal{F}_n^X = \sigma(X_0, \dots, X_n))_{n=0}^\infty.$$

$\mathcal{F}^X$  is called **the canonical filtration of  $X$** .

**Definition 3.3.** A random process  $X$  is a **martingale (with respect to  $\mathcal{F}$ )** if for any  $m \leq n$ ,

$$\mathbb{E}[X_n | \mathcal{F}_m] = X_m.$$

**Definition 3.4.** A random sequence  $X = (X_n)_{n=0}^\infty$  is called **a positive martingale (with respect to  $\mathcal{F}$ )** if  $X$  is adapted,  $X_n \geq 0$  and for any  $m \leq n$ ,

$$\mathbb{E}[X_n | \mathcal{F}_m] = X_m.$$

**Remark 3.1.** If  $X$  is a martingale with respect to  $\mathcal{F}$ , it need not be a martingale with respect to its own filtration  $\mathcal{F}^X \prec \mathcal{F}$ .

**Definition 3.5.** • A random process  $X$  is a **submartingale (with respect to  $\mathcal{F}$ )** if for any  $m \leq n$ ,

$$\mathbb{E}[X_n | \mathcal{F}_m] \geq X_m.$$

• We say that  $X$  is a **supermartingale** if  $-X$  is a submartingale.



**Remark 3.2.** A martingale is a random process with constant expectation:  $\mathbb{E}[X_n] = \mathbb{E}[X_0]$ . Submartingales have non-decreasing expectations:  $\mathbb{E}[X_n] \geq \mathbb{E}[X_m]$  for any  $m \leq n$ .

The most basic example of a random process  $X$  is a *random walk*:

$$X_n = Z_1 + \cdots + Z_n \quad \text{for } n \geq 1,$$

where  $Z_k$  are i.i.d. rv in  $L^1$ . With respect to its canonical filtration  $\mathcal{F}^X$ ,

- $X$  is a martingale if  $\mathbb{E}[Z_k] = 0$ .
- $X$  is a supermartingale if  $\mathbb{E}[Z_k] \leq 0$ .
- $X$  is a submartingale if  $\mathbb{E}[Z_k] \geq 0$ .

**Proposition 3.3** (Convex transformations). Let  $\varphi : \mathbb{R} \rightarrow \mathbb{R}$  be a convex function so that  $\mathbb{E}[\varphi(X_n)] < \infty$  for any  $n \in \mathbb{N}_0$ . We denote  $\varphi(X) = (\varphi(X_n))_{n=0}^\infty$ .

- If  $X$  is a martingale, then  $\varphi(X)$  is a submartingale.
- If  $\varphi$  is non-decreasing and  $X$  is a submartingale, then  $\varphi(X)$  is also a submartingale.

*Proof.* These claims follow directly from Jensen's inequality; see Lemma 2.12. □