

Prediction for Large Multivariate Spatial Datasets

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Reduce cokriging to bikriging by using the primary and an aggregated variable which consists of a linear combination of the secondary variables.

Joint work with Marc Genton.

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Univariate Spatial Process

Univariate spatial process on $\mathcal{D} \subset \mathbb{R}^d$:

$$Z(\mathbf{s}) = \mathbf{m}(\mathbf{s})^T \boldsymbol{\beta} + Y(\mathbf{s}), \quad E(Y) = 0, \quad \text{Var}(Y) = \Sigma$$

Predict $Z(\mathbf{s}_p)$ based on observations $\mathbf{Z} = (Z(\mathbf{s}_1), \dots, Z(\mathbf{s}_n))^T$.

Kriging with many observations (n large or even huge):

- Backfitting (iterating over fixed effects and spatial term)
- Tapering (introducing sparsity in Σ)

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Multivariate Spatial Process

Multivariate (zero mean) spatial process on $\mathcal{D} \subset \mathbb{R}^d$:

primary variable $Y_0(\cdot)$
secondary variables $Y_1(\cdot), \dots, Y_\ell(\cdot), \ell > 1$

Predict $Y_0(\mathbf{s}_p) = Y_p$ based on

$$\mathbf{Y}_0 = (Y_0(\mathbf{s}_1), \dots, Y_0(\mathbf{s}_n))^T$$

$$\mathbf{Y}_k = (Y_k(\mathbf{s}_{n+1}), \dots, Y_k(\mathbf{s}_{n+m}))^T, \quad 1 \leq k \leq \ell$$

Kriging with many observations (n, m large or even huge):

- Backfitting?
- Tapering?

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Multivariate Spatial Process

With $\mathbf{Y}_g = \mathbf{Y}_1$, $\mathbf{Y}_g = (\mathbf{Y}_1^T, \dots, \mathbf{Y}_\ell^T)^T, \dots$ write

$$\text{Var} \begin{pmatrix} Y_p \\ \mathbf{Y}_0 \\ \mathbf{Y}_g \end{pmatrix} = \begin{pmatrix} \Sigma_{pp} & \Sigma_{p0} & \Sigma_{pg} \\ \Sigma_{0p} & \Sigma_{00} & \Sigma_{0g} \\ \Sigma_{gp} & \Sigma_{g0} & \Sigma_{gg} \end{pmatrix}$$

BLUP of Y_p given \mathbf{Y}_0 and \mathbf{Y}_g is

$$(\Sigma_{p0} \ \Sigma_{pg}) \begin{pmatrix} \Sigma_{00} & \Sigma_{0g} \\ \Sigma_{g0} & \Sigma_{gg} \end{pmatrix}^{-1} \begin{pmatrix} \mathbf{Y}_0 \\ \mathbf{Y}_g \end{pmatrix}$$

and its MSPE is

$$\Sigma_{pp} - (\Sigma_{p0} \ \Sigma_{pg}) \begin{pmatrix} \Sigma_{00} & \Sigma_{0g} \\ \Sigma_{g0} & \Sigma_{gg} \end{pmatrix}^{-1} \begin{pmatrix} \Sigma_{0p} \\ \Sigma_{gp} \end{pmatrix}$$

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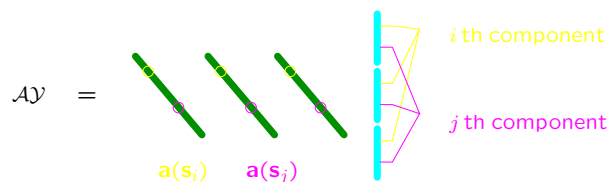
Idea of Aggregation–Cokriging

Instead of all secondary variables, use only a linear combination:

$$Y_g(\mathbf{s}_i) = a_1(\mathbf{s}_i)Y_1(\mathbf{s}_i) + \dots + a_\ell(\mathbf{s}_i)Y_\ell(\mathbf{s}_i)$$

for well-chosen (optimal) weights $a_1(\mathbf{s}_i), \dots, a_\ell(\mathbf{s}_i)$.

Introduce the aggregation matrix $\mathcal{A} \in \mathbb{R}^{m \times m\ell}$, such that the linear combination is $\mathcal{A}\mathcal{Y}$, with $\mathcal{Y} = (\mathbf{Y}_1^T, \dots, \mathbf{Y}_\ell^T)^T$.



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Idea of Aggregation–Cokriging

Minimizing the MSPE over all admissible \mathcal{A} is often infeasible.

Base the choice of the weights on intuitive ideas:

- Principal component analysis (PCA)
- Canonical correlation analysis (CCA)
- Maximum covariance analysis (MCA)
- ...

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Aggregation

Aggregation cokriging based on the weights:

$$\mathbf{a}(\mathbf{s}_i) = \underset{\mathbf{x}}{\operatorname{argmax}} \mathbf{x}^T \mathbf{A}_i \mathbf{x} \quad \text{s.t.} \quad \mathbf{x}^T \mathbf{B}_i \mathbf{x} = 1$$

$$\rightsquigarrow \text{AGG}(\mathbf{A}_i, \mathbf{B}_i)\text{-cokriging}$$

$$\mathbf{a}(\mathbf{s}_i) = \underset{\mathbf{x}}{\operatorname{argmin}} \mathbf{x}^T \mathbf{C}_i \mathbf{x} \quad \text{s.t.} \quad \mathbf{x}^T \boldsymbol{\omega} = 1$$

$$\rightsquigarrow \text{AGG}(\mathbf{C}_i, \boldsymbol{\omega})\text{-cokriging}$$

PCA, CCA, MCA ideas can be written as above.

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Aggregation

Examples:

- Bikriging with variable k : $\text{AGG}(\mathbf{I}, \mathbf{e}_k)\text{-cokriging}$
- Equal weighting, $\mathbf{a} \propto \mathbf{1}$: $\text{AGG}(\mathbf{1}\mathbf{1}^T, \mathbf{I})\text{-cokriging}$
- MCA: $\text{AGG}([\Sigma_{ps}\Sigma_{rp}], \mathbf{I})\text{-cokriging}$

Aggregation cokriging based on the aggregation matrix \mathcal{A} can be written as $\text{AGG}(\mathbf{a}_i \mathbf{a}_i^T, \mathbf{I})\text{-cokriging}$ and vice versa.

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Optimality Results

Assume $\Sigma_{rp} = \Sigma_{1p}$ and $\Sigma_{r0} = \Sigma_{10}$, $r = 2, \dots, \ell$.

Comparing the MSPE of two aggregation cokriging schemes based on \mathcal{A} and \mathcal{B} reduces to the evaluation of expressions of the form

$$\sum_{r=1}^{\ell} \sum_{s=1}^{\ell} \Sigma_{rs} \circ \text{matrix depending on } \mathcal{A} \text{ and } \mathcal{B}$$

Expression can be simplified if:

- $\mathbf{a}(\mathbf{s}_i)$ does not depend on \mathbf{s}_i
- $\Sigma_{rs} = \Sigma_{12}$, $r \neq s = 1, \dots, \ell$
- $\Sigma_{rr} = \Sigma_{11}$, $r = 1, \dots, \ell$

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Optimality Results

Example:

$(\Sigma_{rp} = \Sigma_{1p}, \Sigma_{r0} = \Sigma_{10}, \Sigma_{rr} = \Sigma_{11}, \Sigma_{rs} = \Sigma_{12}, r \neq s = 1, \dots, \ell)$

- If $\mathbf{a}^T \mathbf{1} = 0$: $\text{MSPE}_{\text{AGG-cokriging}} = \text{MSPE}_{\text{kriging}}$
- If $|\mathbf{a}^T \mathbf{1}| \leq \sqrt{\mathbf{a}^T \mathbf{a}}$: $\text{MSPE}_{\text{AGG-cokriging}} \leq \text{MSPE}_{\text{bikriging}}$
- If $\mathbf{a} \propto \mathbf{1}$: $\text{MSPE}_{\text{AGG-cokriging}} = \text{MSPE}_{\text{cokriging}}$

If the secondary variables do not have a common (cross-)covariance structure, then we cannot derive theoretical results.

Simulations indicate that AGG-cokriging is still very competitive.

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Optimality Results

Assume an intrinsic type model

$$\text{Var} \begin{pmatrix} Y_p \\ \mathbf{Y}_0 \\ \mathcal{Y} \end{pmatrix} = \begin{pmatrix} \Sigma_{pp} & \Sigma_{p0} & \boldsymbol{\omega}^T \otimes \Sigma_{pc} \\ \Sigma_{0p} & \Sigma_{00} & \boldsymbol{\omega}^T \otimes \Sigma_{0c} \\ \boldsymbol{\omega} \otimes \Sigma_{cp} & \boldsymbol{\omega} \otimes \Sigma_{c0} & \boldsymbol{\Omega} \otimes \Sigma_{cc} \end{pmatrix}$$

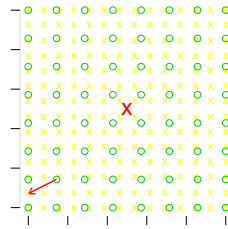
Then:

$\text{AGG}(\boldsymbol{\Omega}, \boldsymbol{\omega})\text{-cokriging}$ minimizes the MSPE based on $\mathbf{Y}_g = \mathcal{A}\mathcal{Y}$.

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Illustration

- Primary variable (○)
- Three secondary variables (×)
- Spherical covariance structures
- No measurement error
- Prediction along \rightarrow and at \times

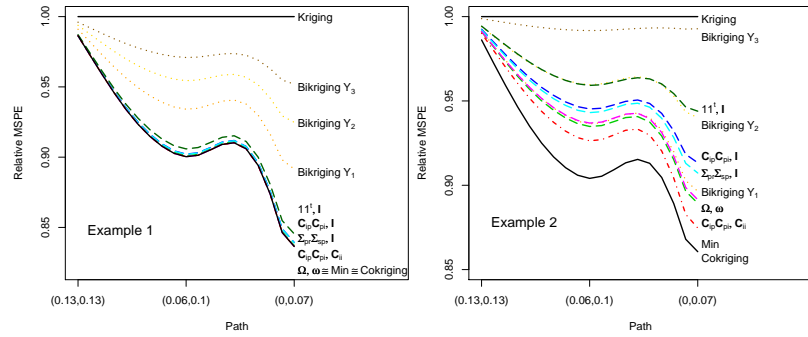


Example 1: Sills: $\begin{pmatrix} 1 & 0.3 & 0.25 & 0.2 \\ 0.3 & 1 & 0.2 & 0.3 \\ 0.25 & 0.2 & 1 & 0.2 \\ 0.2 & 0.3 & 0.2 & 1 \end{pmatrix}$ Ranges: $\begin{pmatrix} 1.2 & 0.7 & 0.7 & 0.7 \\ 0.6 & 0.6 & 0.6 & 0.6 \\ 0.6 & 0.6 & 0.6 & 0.6 \\ 0.6 & 0.6 & 0.6 & 0.6 \end{pmatrix}$

Example 2: Sills: $\begin{pmatrix} 1 & 0.3 & 0.3 & 0.1 \\ 0.3 & 1 & 0.3 & 0.2 \\ 0.3 & 0.3 & 1 & 0.3 \\ 0.1 & 0.2 & 0.3 & 1 \end{pmatrix}$ Ranges: $\begin{pmatrix} 1.0 & 0.6 & 0.5 & 0.4 \\ 0.6 & 0.5 & 0.3 & 0.2 \\ 0.5 & 0.3 & 0.2 & 0.1 \\ 0.4 & 0.2 & 0.1 & 0.1 \end{pmatrix}$

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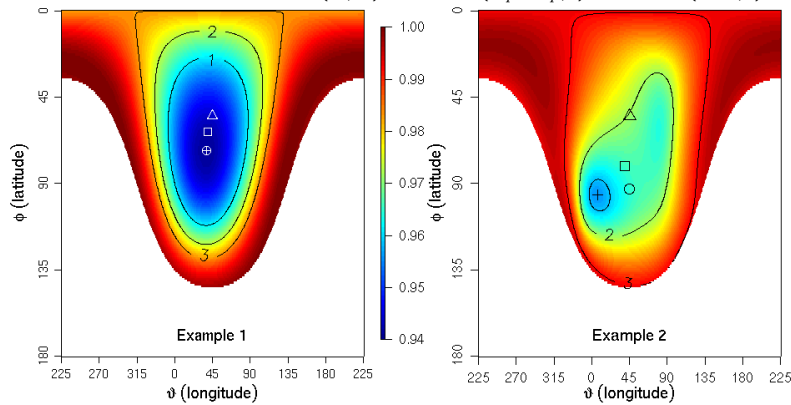
Illustration



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Illustration

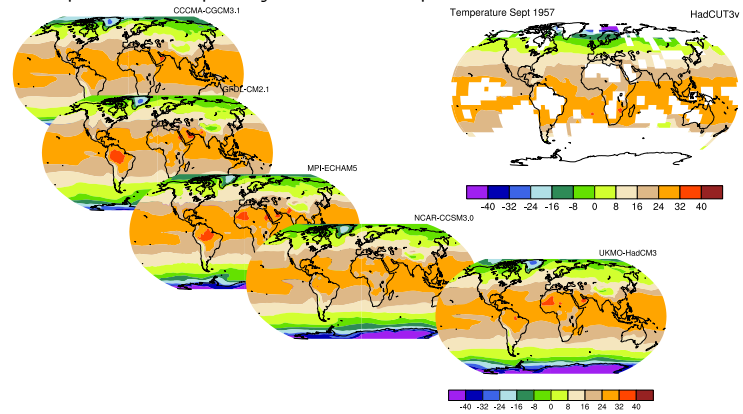
+ : minimum, ○ : $AGG(\Omega, \omega)$, □ : $AGG(\Sigma_{pr}\Sigma_{sp}, \mathbf{I})$, △ : $AGG(\mathbf{11}^T, \mathbf{I})$



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Application

Imputation of sparsely observed temperature fields.



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Application

Issues:

- Linking observations with climate realizations:

Use one climate model as observations
"Truth" is known

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Application

Issues:

- Linking observations with climate realizations
- Non-stationarity:

$$T_i(\delta, \vartheta) = f(\delta; \beta_i) \cdot Z_i(\delta, \vartheta)$$

Z_i is an isotropic process on the sphere

$$f(\delta; \beta_1, \dots, \beta_4) = f_\gamma((90 + \delta)/180; \beta_1, \beta_3) + f_\gamma((90 - \delta)/180; \beta_2, \beta_4) + 1$$

with f_γ the density of a gamma random variable.

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Application

Issues:

- Linking observations with climate realizations
- Non-stationarity
- Efficient estimation and valid fits:

Exploit the latitudinal invariance
Fix the range to 30 degrees

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Application

Issues:

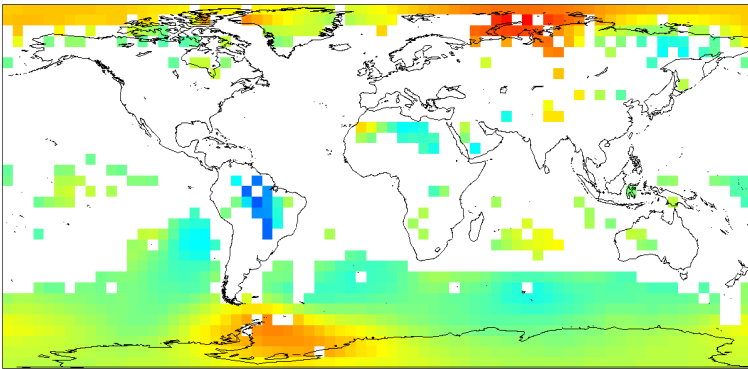
- Linking observations with climate realizations
- Non-stationarity
- Efficient estimation and valid fits
- Data size:

Sparse matrix algebra and `spam`

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Application

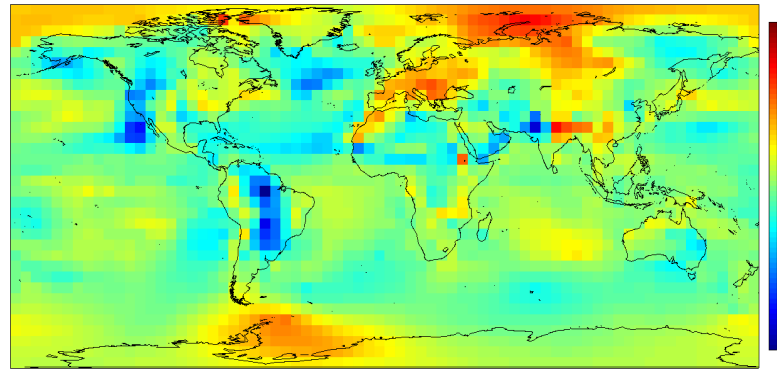
Centered predictions



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Application

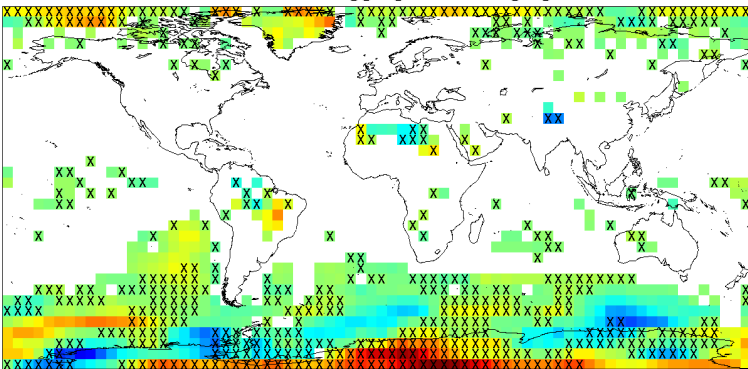
Centered field



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Application

Residuals for aggregation cokriging



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Conclusion

AGG-cokriging is

- based on an intuitive idea
- formalized through simple minimization criteria
- optimal (MSPE sense) for specific covariance structures

Extend AGG-cokriging to

- several linear combinations of secondary variables
- formalize for a set of prediction points
- explore different covariance structures/optimization criteria
- address non-zero means
- address the computational scaling

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