

# Correlated Errors in Geophysical Applications

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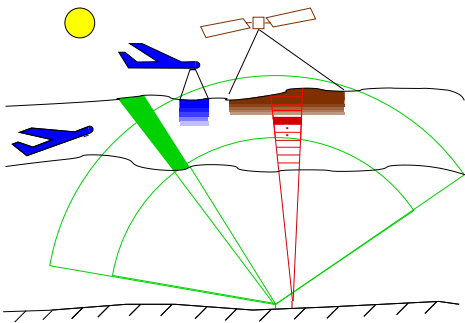
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## Outline

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- Statistical Model
- Parameter estimation
  - Method of Moments
  - Test of Independence
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  - Estimation in Large Systems
- Summary

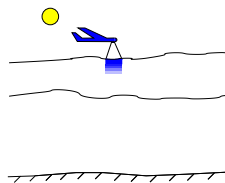
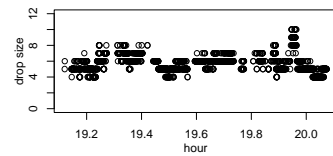
## Example 1

Inverse Problem: drop size retrievals



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## Example 2

Ensemble Kalman filter: Weather forecasting

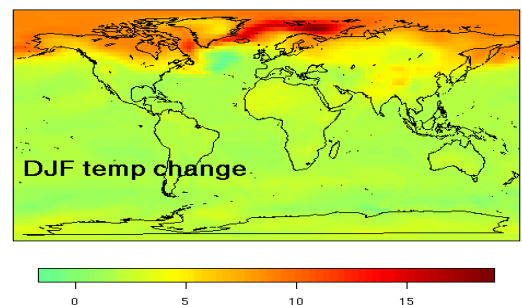
A **numerical model** is used to make short-range forecasts, with new **observations** contributing to **data history** as they become available.

- Surface (towers, ships)
- Altitude (planes, **ballons**)
- Radar
- Satellites

## Example 3

Optimal prediction: climate projection

Precipitation or temperature fields are decomposed into a **large scale trend** and a **small scale variation**.



# Statistical Model

Common notation of the three examples:

$$y_i = F(m) + \varepsilon_i$$

$$\mathbf{y} = F(\mathbf{x}) + \varepsilon$$

$$Y(\mathbf{x}_i) = f(\mathbf{x}_i) + \varepsilon(\mathbf{x}_i)$$

Assumptions on the error process:

$$E(\varepsilon) = \mathbf{0} \quad \text{and} \quad \text{Cov}(\varepsilon) = \Sigma$$

$$\varepsilon \sim \mathcal{N}(\mathbf{0}, \Sigma) \quad \text{or} \quad \varepsilon \sim \mathcal{G}, \quad \mathcal{G} \text{ symmetric}$$

↪ Characterize the "error" process  $\varepsilon$

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# Method of Moments

Objective:

a parametric description of  $\Sigma$  with  $\Sigma_{ij} = \text{Cov}(\varepsilon(\mathbf{x}_i), \varepsilon(\mathbf{x}_j))$ .

Without distributional assumptions, analysis is usually based on the variogram:

$$2\gamma(\mathbf{x}_i - \mathbf{x}_j; \theta) = \text{Var}(\varepsilon(\mathbf{x}_i) - \varepsilon(\mathbf{x}_j))$$

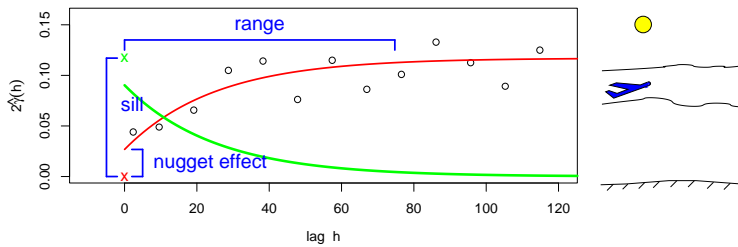
With sample measurement errors a sample variogram is obtained.

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# Variogram Fitting

We fit a parametric model  $2\gamma(\cdot; \theta)$ :

$$\hat{\theta}_{\text{MoM}} \text{ minimizes } \ell(2\hat{\gamma}(\mathbf{h}) - 2\gamma(\mathbf{h}; \theta))$$



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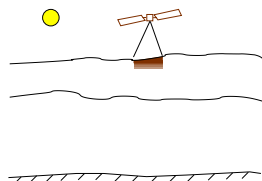
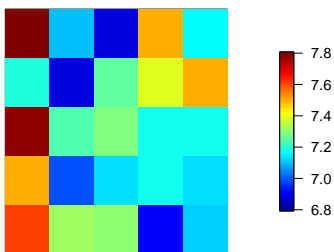
# (Dis)Advantages

- + classical geostatistical approach
- + no distributional assumptions on the error required
- + highly robust versions exist
- difficult to describe uncertainty
- two-step procedure with many "hidden parameters"

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# Test of Independence

Do we have spatial dependence?

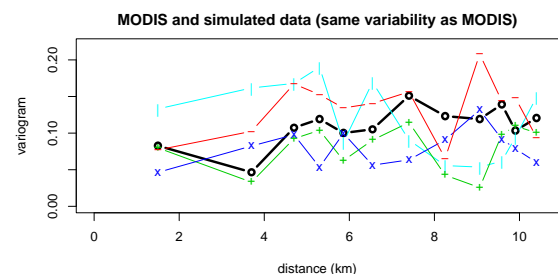
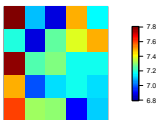


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# Test of Independence

Variogram of white noise  $\varepsilon \sim \mathcal{N}(0, \sigma^2)$  is

$$2\gamma(\mathbf{x}_i - \mathbf{x}_j; \theta) = \text{Var}(\varepsilon(\mathbf{x}_i) - \varepsilon(\mathbf{x}_j)) \equiv 2\sigma^2$$



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## Maximum Likelihood

We assume a distribution for our model:

$$\mathbf{y} = F(\mathbf{x}) + \varepsilon \quad \varepsilon \sim \mathcal{N}(\mathbf{0}, \Sigma(\theta))$$

$$p(\mathbf{y}; \theta) \propto |\Sigma(\theta)|^{-1/2} \exp\left(-\frac{1}{2}(\mathbf{y} - F(\mathbf{x}))^T \Sigma(\theta)^{-1}(\mathbf{y} - F(\mathbf{x}))\right)$$

$$\hat{\theta}_{\text{MLE}} \text{ maximizes } \log p(\mathbf{y}; \theta)$$

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## (Dis)Advantages

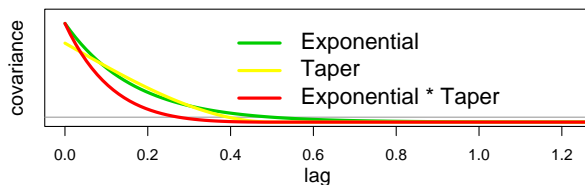
- + one-step procedure
- + straight-forward inference on parameters
- + can be extended with parameterized large scale structures
- distributional assumptions on the error required
- computationally expensive

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## Large Systems

Maximum Likelihood is computationally expensive.

(Motivated from a prediction point of view) we approximate  $\Sigma$ .



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Let  $\mathbf{T}$  be a "sparse" positive definite matrix.

Base likelihood on  $\tilde{\Sigma} = \Sigma \circ \mathbf{T}$  and use sparse matrix techniques.

Consistency and optimality are preserved.

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## Summary

Characterisation of correlated processes (spatial processes)

Geostatistics traditionally deals with correlated processes

Efficient methods for describing the process, but . . .

Enough gaps for further research . . .

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