# SINGULAR PERTURBATIONS OF SOME NONLINEAR PROBLEMS 

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Dedicated to Prof. V.V. Zhikov on the occasion of his 70th birthday


#### Abstract

In this paper we deal with singular perturbations of nonlinear problems depending on a small parameter $\varepsilon>0$. First we consider the abstract theory of singular perturbations of variational inequalities involving some nonlinear operators, defined in Banach spaces, and describe the asymptotic behaviour of these solutions when $\varepsilon \rightarrow 0$. Then these abstract results are applied to some boundary value problems.


## 1. Introduction

The goal of this paper is to study the asymptotic behaviour of singular perturbations problems when a parameter $\varepsilon$ goes towards 0 . Our results are very general but we have more particularly in mind anisotropic cases where $\varepsilon$ only acts on some variables of a domain $\Omega \subset \mathbb{R}^{n}$ ( $n$ is an integer) where we consider the partial differential equations. To be more precise we can take,

[^0]as a model, the diffusion problem defined in the unit square $\Omega=(0,1) \times(0,1)$
\[

$$
\begin{cases}-\varepsilon^{2} \partial_{x_{1}}^{2} u_{\varepsilon}-\partial_{x_{2}}^{2} u_{\varepsilon}=f & \text { in } \Omega,  \tag{1.1}\\ u_{\varepsilon}=0 & \text { on } \partial \Omega\end{cases}
$$
\]

where $\varepsilon>0$ and $f$ represents the source term. We assume that the diffusion in the $x_{1}$-direction is negligible with respect to the other direction when $\varepsilon \rightarrow 0$. Formally the natural limit of $u_{\varepsilon}$ is a function $u_{0}$ defined on the sections $\left\{x_{1}\right\} \times(0,1)$ for a.e. $x_{1} \in(0,1)$ as a solution of

$$
\begin{cases}-\partial_{x_{2}}^{2} u_{0}\left(x_{1}, \cdot\right)=f\left(x_{1}, \cdot\right) & \text { in }(0,1)  \tag{1.2}\\ u_{0}\left(x_{1}, \cdot\right)=0 & \text { on }\{0,1\}\end{cases}
$$

Note that the variable $x_{1}$ plays a role of a parameter. It is clear that if $f$ (not identically equal to 0 ) is independent of $x_{1}$, i.e. $f=f\left(x_{2}\right)$, then $u_{0} \notin H_{0}^{1}(\Omega)$. This prevents the convergence $u_{\varepsilon} \rightarrow u_{0}$ to occur in $H^{1}(\Omega)$. From this remark we may discuss many issues concerning this convergence.

In this note we begin by dealing with abstract singular perturbations problems of variational inequalities. Our approach has the advantage to include in a short theory a wide class of problems spread in the literature. We give then some applications of it.

In the literature, linear elliptic, parabolic and hyperbolic problems defined on arbitrary domains are analyzed in different contexts and the convergence $u_{\varepsilon} \rightarrow u_{0}$ is obtained in different norms. A boundary layer may occur at the lateral boundary of cylindrical domains $(\{0,1\} \times(0,1)$ for the above example). The convergence in Sobolev spaces may be shown in regions far from this lateral boundary. We may see this clearly when our perturbed problem satisfies some cylindrical symmetries. This means that $f=f\left(x_{2}\right)$ in the above example. In this case $u_{\varepsilon}$ converges towards $u_{0}$ at an exponential rate. For more details we refer the reader to $[1,2,3,5,6,7,8,9,10,11]$.

An abstract approach to this theory was also given in $[14,16]$ where the following operator equation is considered

$$
\begin{equation*}
\varepsilon A u_{\varepsilon}+B u_{\varepsilon}=f \tag{1.3}
\end{equation*}
$$

with $A$ and $B$ linear operators defined on Hilbert spaces. This approach covers diagonal structure problems as problem (1.1). The authors also showed, as in the case of partial differential equations, that $u_{\varepsilon}$ converges towards $u_{0}$ solution to

$$
B u_{0}=f
$$

when $\varepsilon \rightarrow 0$. There are also some previous works on singular perturbations of variational inequalities, i.e. when (1.3) is replaced by

$$
\begin{equation*}
\left(\varepsilon A u_{\varepsilon}, v-u_{\varepsilon}\right)+\left(B u_{\varepsilon}, v-u_{\varepsilon}\right) \geq\left(f, v-u_{\varepsilon}\right), \quad \forall v \in K \tag{1.4}
\end{equation*}
$$

where $K$ is some nonempty closed convex set (cf. [12, 13, 15]). In [15] this abstract approach is established to investigate the isotropic singular perturbations problems.

In order to cover a larger class of problems by an abstract theory, we will deal with the variational inequality (1.4) when $A$ and $B$ are nonlinear operators defined on different Banach spaces $V$ and $W$ respectively, which in particular applies to the anisotropic singular perturbations problems. This is what we will see in the next section. In the last section, the first example is devoted to show that these results also cover the isotropic case. Then some examples of anisotropic singular perturbations problems are introduced in order to illustrate some points of the theory as, for instance, the lack of compactness.

## 2. Abstract singular perturbations problems

Let $V$ and $W$ be two reflexive separable Banach spaces equipped with the norms $|\cdot|_{V}$ and $|\cdot|_{W}$ respectively. We suppose that the space $V \cap W$ is dense in $V$ and $W$, and is equipped with the norm

$$
|\cdot|_{V \cap W}=|\cdot|_{V}+|\cdot|_{W} .
$$

Of course the $V \cap W$ is a Banach space equipped with the previous norm. For any space $X$, we denote by $\langle\cdot, \cdot\rangle_{X}$ the duality pairing between $X^{\prime}$ and $X$ where $X^{\prime}$ is the dual of $X$. It is clear that

$$
V \cap W \subset V, W \text { and } V^{\prime}, W^{\prime} \subset(V \cap W)^{\prime}
$$

Moreover one can check that $(V \cap W)^{\prime}=V^{\prime}+W^{\prime}$. We consider two nonlinear operators $A$ and $B$ such that

$$
A: V \rightarrow V^{\prime}, \quad B: W \rightarrow W^{\prime} .
$$

We suppose that $A, B$ are monotone, that is to say that

$$
\begin{align*}
& \langle A u-A v, u-v\rangle_{V} \geq 0, \quad \forall u, v \in V,  \tag{2.1}\\
& \langle B u-B v, u-v\rangle_{W} \geq 0, \quad \forall u, v \in W . \tag{2.2}
\end{align*}
$$

We denote by $K \neq \varnothing$ a closed convex set of $V \cap W$ and for $A, B$ we make the following coerciveness assumption. We suppose that for some $v_{0} \in K$
one has

$$
\begin{align*}
& \frac{\left\langle A u-A v_{0}, u-v_{0}\right\rangle_{V}}{\left|u-v_{0}\right|_{V}} \rightarrow+\infty \text { when }\left|u-v_{0}\right|_{V} \rightarrow+\infty, \quad u \in K  \tag{2.3}\\
& \frac{\left\langle B u-B v_{0}, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{W}} \rightarrow+\infty \text { when }\left|u-v_{0}\right|_{W} \rightarrow+\infty, \quad u \in K \tag{2.4}
\end{align*}
$$

Remark 1. If $K$ is bounded in $V$ (resp. in $W$ ) we will not need the assumption (2.3) (resp. (2.4)). Note also that for some $v_{0} \in K$ they are equivalent with

$$
\begin{align*}
& \frac{\left\langle A u, u-v_{0}\right\rangle_{V}}{\left|u-v_{0}\right|_{V}} \rightarrow+\infty \text { when }\left|u-v_{0}\right|_{V} \rightarrow+\infty, \quad u \in K  \tag{2.5}\\
& \frac{\left\langle B u, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{W}} \rightarrow+\infty \text { when }\left|u-v_{0}\right|_{W} \rightarrow+\infty, \quad u \in K \tag{2.6}
\end{align*}
$$

In addition we assume that
$A$ sends bounded sets of $V$ in bounded sets of $V^{\prime}$,
$B$ sends bounded sets of $W$ in bounded sets of $W^{\prime}$,

This last assumption means that - for instance for $A$ -

$$
t \mapsto\langle A(u+t v), w\rangle_{V} \text { is continuous on } \mathbb{R}, \quad \forall u, v, w \in V
$$

Under the assumptions above we have:
Theorem 1. For $f \in(V \cap W)^{\prime}$ and $\varepsilon>0$ there exists $u_{\varepsilon}$ solution to

$$
\left\{\begin{array}{l}
\varepsilon\left\langle A u_{\varepsilon}, v-u_{\varepsilon}\right\rangle_{V}+\left\langle B u_{\varepsilon}, v-u_{\varepsilon}\right\rangle_{W} \geq\left\langle f, v-u_{\varepsilon}\right\rangle_{V \cap W}, \forall v \in K  \tag{2.10}\\
u_{\varepsilon} \in K
\end{array}\right.
$$

Moreover if $A$ or $B$ is strictly monotone (i.e. if one of the inequalities (2.1), (2.2) is strict for $u \neq v$ ) the solution is unique.

Proof. We consider $A_{\varepsilon}$ the operator defined by

$$
\begin{aligned}
A_{\varepsilon}: V \cap W & \rightarrow(V \cap W)^{\prime}=V^{\prime}+W^{\prime} \\
v & \mapsto \varepsilon A v+B v
\end{aligned}
$$

This operator is monotone, hemicontinuous and coercive on $K$. For this last point, by the coerciveness assumptions of $A$ and $B$, for every $M>0$ there exist $\delta_{1}(M), \delta_{2}(M) \geq 1$ such that

$$
\begin{equation*}
\left|u-v_{0}\right|_{V} \geq \delta_{1}(M) \Rightarrow \frac{\left\langle\varepsilon A u, u-v_{0}\right\rangle_{V}}{\left|u-v_{0}\right|_{V}} \geq M \tag{2.11}
\end{equation*}
$$

$$
\begin{equation*}
\left|u-v_{0}\right|_{W} \geq \delta_{2}(M) \Rightarrow \frac{\left\langle B u, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{W}} \geq M \tag{2.12}
\end{equation*}
$$

Since $A, B$ are bounded there exist constants $C_{A}, C_{B}$ such that

$$
\begin{aligned}
& \left|u-v_{0}\right|_{V} \leq \delta_{1}(M) \Rightarrow\left|\left\langle\varepsilon A u, u-v_{0}\right\rangle_{V}\right| \leq C_{A}(M), \\
& \left|u-v_{0}\right|_{W} \leq \delta_{2}(M) \Rightarrow\left|\left\langle B u, u-v_{0}\right\rangle_{W}\right| \leq C_{B}(M) .
\end{aligned}
$$

Choose

$$
\begin{aligned}
\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W} \geq & 2 \delta_{1}(M)+2 \delta_{2}(M)+\delta_{1}\left(2 M+2 C_{B}(M)\right) \\
& +\delta_{2}\left(2 M+2 C_{A}(M)\right)
\end{aligned}
$$

Of course one has either $\left|u-v_{0}\right|_{V} \geq \delta_{1}(M)$ or $\left|u-v_{0}\right|_{W} \geq \delta_{2}(M)$. Suppose for instance that $\left|u-v_{0}\right|_{V} \geq \delta_{1}(M)$, the other case being the same. If moreover $\left|u-v_{0}\right|_{W} \geq \delta_{2}(M)$, from (2.11), (2.12) one has

$$
\begin{aligned}
& \frac{\left\langle\varepsilon A u, u-v_{0}\right\rangle_{V}+\left\langle B u, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W}} \\
& =\frac{\left|u-v_{0}\right|_{V}}{\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W}} \cdot \frac{\left\langle\varepsilon A u, u-v_{0}\right\rangle_{V}}{\left|u-v_{0}\right|_{V}} \\
& +\frac{\left|u-v_{0}\right|_{W}}{\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W}} \cdot \frac{\left\langle B u, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{W}} \geq M
\end{aligned}
$$

If $\left|u-v_{0}\right|_{W} \leq \delta_{2}(M)$ then one has

$$
\left|u-v_{0}\right|_{V} \geq \delta_{2}(M), \delta_{1}\left(2 M+2 C_{B}(M)\right)
$$

so that

$$
\begin{aligned}
& \frac{\left\langle\varepsilon A u, u-v_{0}\right\rangle_{V}+\left\langle B u, u-v_{0}\right\rangle_{W}}{\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W}} \\
\geq & \frac{\left|u-v_{0}\right|_{V}}{\left|u-v_{0}\right|_{V}+\left|u-v_{0}\right|_{W}}\left\{2 M+2 C_{B}(M)\right\}-C_{B}(M) \\
\geq & \frac{1}{2}\left\{2 M+2 C_{B}(M)\right\}-C_{B}(M) \geq M
\end{aligned}
$$

This shows the coerciveness of $A_{\varepsilon}$. The existence of $u_{\varepsilon}$ follows from the classical theory of variational inequalities.

Remark 2. When $K=V \cap W$ one sees by taking $v=u_{\varepsilon} \pm w, w \in K$ that $u_{\varepsilon}$ is solution to

$$
\left\{\begin{array}{l}
\varepsilon A u_{\varepsilon}+B u_{\varepsilon}=f  \tag{2.13}\\
u_{\varepsilon} \in V \cap W
\end{array}\right.
$$

We are now interested in studying the behaviour of $u_{\varepsilon}$ when $\varepsilon \rightarrow 0$. Note that this is not possible in general. Indeed, taking for instance $V$ a Hilbert space, $A=$ the identity, $B=0, f \in V^{\prime}=V$ we can see that the solution of (2.13) is given by $u_{\varepsilon}=f / \varepsilon$ and $\left(u_{\varepsilon}\right)_{\varepsilon}$ has no limit. In what follows we will assume that

$$
\begin{equation*}
f \in W^{\prime} \tag{2.14}
\end{equation*}
$$

The essential convergences are given as follows:
Theorem 2. Suppose that $f \in W^{\prime}$ and let $u_{\varepsilon}$ be solution to (2.10). Then we have when $\varepsilon \rightarrow 0$

$$
\begin{align*}
& \text { (i) } u_{\varepsilon} \text { is bounded in } W \text { independently of } \varepsilon \text {, }  \tag{2.15}\\
& \text { (ii) } \varepsilon u_{\varepsilon} \rightarrow 0 \text { in } V  \tag{2.16}\\
& \text { (iii) } \varepsilon A u_{\varepsilon} \rightarrow 0 \text { in } V^{\prime}  \tag{2.17}\\
& \text { (iv) }\left\langle\varepsilon A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \rightarrow 0 \tag{2.18}
\end{align*}
$$

Proof. Proof of (i). Choose $v_{0} \in K$, such that (2.5) and (2.6) hold. Suppose that $\left|u_{\varepsilon}-v_{0}\right|_{W}$ is unbounded. For some sequence $\varepsilon_{k} \rightarrow 0$ one has then

$$
\left|u_{\varepsilon_{k}}-v_{0}\right|_{W} \rightarrow+\infty
$$

Taking $v=v_{0}$ in (2.10) we derive

$$
\begin{aligned}
\varepsilon_{k}\left\langle A u_{\varepsilon_{k}}, u_{\varepsilon_{k}}-v_{0}\right\rangle_{V}+\left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}-v_{0}\right\rangle_{W} & \leq\left\langle f, u_{\varepsilon_{k}}-v_{0}\right\rangle_{W} \\
& \leq|f|_{W^{\prime}}\left|u_{\varepsilon_{k}}-v_{0}\right|_{W}
\end{aligned}
$$

It follows that

$$
\begin{equation*}
\frac{\varepsilon_{k}\left\langle A u_{\varepsilon_{k}}, u_{\varepsilon_{k}}-v_{0}\right\rangle_{V}}{\left|u_{\varepsilon_{k}}-v_{0}\right|_{W}}+\frac{\left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}-v_{0}\right\rangle_{W}}{\left|u_{\varepsilon_{k}}-v_{0}\right|_{W}} \leq|f|_{W^{\prime}} \tag{2.19}
\end{equation*}
$$

If $\left|u_{\varepsilon_{k}}-v_{0}\right|_{V}$ is bounded then

$$
\frac{\varepsilon_{k}\left\langle A u_{\varepsilon_{k}}, u_{\varepsilon_{k}}-v_{0}\right\rangle_{V}}{\left|u_{\varepsilon_{k}}-v_{0}\right|_{W}} \rightarrow 0
$$

else by the coerciveness of $A$ this term is nonnegative for some $k$ large enough. In both cases, due to the coerciveness of $B$, the left hand side of (2.19) is unbounded which is impossible. This proves (2.15).

Proof of (ii). Since $u_{\varepsilon}$ is bounded in $W$, and by consequence $B u_{\varepsilon}$ is bounded in $W^{\prime}$, we derive from (2.10) written for $v=v_{0}$ that

$$
\begin{equation*}
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}-v_{0}\right\rangle_{V} \leq C \tag{2.20}
\end{equation*}
$$

for some constant $C$ independent of $\varepsilon$. If $\left(u_{\varepsilon}-v_{0}\right)$ is bounded in $V$ it is clear that $\varepsilon u_{\varepsilon}=\varepsilon\left(u_{\varepsilon}-v_{0}\right)+\varepsilon v_{0} \rightarrow 0$. Else we have from (2.5), (2.20) -up to a subsequence-

$$
\varepsilon\left|u_{\varepsilon}-v_{0}\right|_{V} \leq C \frac{\left|u_{\varepsilon}-v_{0}\right|_{V}}{\left\langle A u_{\varepsilon}, u_{\varepsilon}-v_{0}\right\rangle_{V}} \rightarrow 0
$$

and the result follows as in the previous case.
Proof of (iii) and (iv). We first show that $\varepsilon A u_{\varepsilon} \rightharpoonup 0$ in $V^{\prime}$. Let $v \in \mathrm{~V}$. From the monotonicity of $A$ we have

$$
\begin{equation*}
\varepsilon\left\langle A u_{\varepsilon}-A v, u_{\varepsilon}-v\right\rangle_{V} \geq 0 \tag{2.21}
\end{equation*}
$$

whence

$$
\begin{equation*}
\varepsilon\left\langle A u_{\varepsilon}, v\right\rangle_{V} \leq \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V}+\left\langle A v, \varepsilon\left(v-u_{\varepsilon}\right)\right\rangle_{V} . \tag{2.22}
\end{equation*}
$$

For $v_{0} \in K$ we derive from (2.20) that

$$
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \leq\left\langle\varepsilon A u_{\varepsilon}, v_{0}\right\rangle_{V}+C
$$

and thus, using (2.22), we get

$$
\begin{equation*}
\varepsilon\left\langle A u_{\varepsilon}, v-v_{0}\right\rangle_{V} \leq C+\left\langle A v, \varepsilon\left(v-u_{\varepsilon}\right)\right\rangle_{V} \tag{2.23}
\end{equation*}
$$

where $C$ is a constant independent of $\varepsilon$. Choosing $v \in v_{0}+\mathcal{B}_{1}$, where $\mathcal{B}_{1}$ is the unit ball of $V$, we arrive to

$$
\varepsilon\left\langle A u_{\varepsilon}, v_{1}\right\rangle_{V} \leq C^{\prime}, \quad \forall v_{1} \in \mathcal{B}_{1}
$$

where $C^{\prime}$ is independent of $\varepsilon$. Thus $\varepsilon A_{\varepsilon}$ is bounded in $V^{\prime}$ and -for some subsequence-

$$
\varepsilon A u_{\varepsilon} \rightharpoonup \psi \text { in } V^{\prime}
$$

Passing to the limit in (2.23) we derive

$$
\left\langle\psi, v-v_{0}\right\rangle_{V} \leq C, \quad \forall v \in V
$$

and thus $\psi=0$. By the uniqueness of the possible limits we have shown that

$$
\varepsilon A u_{\varepsilon} \rightharpoonup 0 \text { in } V^{\prime} .
$$

For any $v \in K$ we have by (2.10) and the monotonicity of $B$

$$
\begin{align*}
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} & \leq\left\langle\varepsilon A u_{\varepsilon}, v\right\rangle_{V}+\left\langle f, u_{\varepsilon}-v\right\rangle_{W}+\left\langle B u_{\varepsilon}, v-u_{\varepsilon}\right\rangle_{W} \\
& \leq\left\langle\varepsilon A u_{\varepsilon}, v\right\rangle_{V}+\left\langle f, u_{\varepsilon}-v\right\rangle_{W}+\left\langle B v, v-u_{\varepsilon}\right\rangle_{W} \tag{2.24}
\end{align*}
$$

Let $\left(\varepsilon_{k}\right)_{k}$ be a sequence such that

$$
\varepsilon_{k}\left\langle A u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{V} \rightarrow \lim _{\varepsilon \rightarrow 0} \sup \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V}
$$

Since $u_{\varepsilon_{k}}$ is bounded in $W$ - extracting if necessary another subsequence one can suppose that

$$
u_{\varepsilon_{k}} \rightharpoonup \tilde{u} \text { in } W
$$

Then passing to the limit in (2.24) written for $\varepsilon_{k}$ we get

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \sup \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \leq\langle f, \tilde{u}-v\rangle_{W}+\langle B v, v-\tilde{u}\rangle_{W}, \forall v \in K \tag{2.25}
\end{equation*}
$$

It is clear that $\tilde{u}$ belongs to $\bar{K}^{W}$, the weak closure of $K$ in $W$ which coincides with its strong closure since $K$ is convex. Thus, there exists a sequence $v_{n} \in K$ such that

$$
v_{n} \rightarrow \tilde{u} \text { in } W
$$

Taking $v=v_{n}$ in (2.25) and passing to the limit we derive

$$
\lim _{\varepsilon \rightarrow 0} \sup \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \leq 0
$$

Passing to the limit in (2.22) we also have

$$
\lim _{\varepsilon \rightarrow 0} \inf \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \geq 0
$$

which proves (iv).
To complete the proof, going back to (2.22) one has for every $v_{1} \in \mathcal{B}_{1}$

$$
\begin{aligned}
\varepsilon\left\langle A u_{\varepsilon}, v_{1}\right\rangle_{V} & \leq \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V}+\left|A v_{1}\right|_{V^{\prime}}\left(\varepsilon+\left|\varepsilon u_{\varepsilon}\right|_{V}\right) \\
& \leq \varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V}+C\left(\varepsilon+\left|\varepsilon u_{\varepsilon}\right|_{V}\right) \rightarrow 0
\end{aligned}
$$

where $C$ is independent of $v_{1}$. This completes the proof of the theorem.
Remark 3. In the case where $K=V \cap W$, from the equation (2.13) one derives that

$$
\begin{equation*}
B u_{\varepsilon}-f \rightarrow 0 \text { in } V^{\prime} \tag{2.26}
\end{equation*}
$$

In addition we have
Theorem 3. Suppose that for some sequence $\varepsilon_{k} \rightarrow 0$ one has

$$
\begin{equation*}
u_{\varepsilon_{k}} \rightharpoonup \tilde{u} \text { in } W \text {. } \tag{2.27}
\end{equation*}
$$

Then $\tilde{u}$ is a solution to the variational inequality

$$
\left\{\begin{array}{l}
\langle B \tilde{u}, v-\tilde{u}\rangle_{W} \geq\langle f, v-\tilde{u}\rangle_{W}, \quad \forall v \in \bar{K}^{W}  \tag{2.28}\\
\tilde{u} \in \bar{K}^{W}
\end{array}\right.
$$

Moreover one has

$$
\begin{equation*}
B u_{\varepsilon_{k}} \rightharpoonup B \tilde{u} \text { in } W^{\prime}, \quad\left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W} \rightarrow\langle B \tilde{u}, \tilde{u}\rangle_{W} \tag{2.29}
\end{equation*}
$$

Proof. Up to a subsequence - still labelled $\varepsilon_{k}$ - one can assume that

$$
B u_{\varepsilon_{k}} \rightharpoonup \chi \text { in } W^{\prime} .
$$

Passing to the limit in (2.10) written for $\varepsilon_{k}$ we obtain (see Theorem 2)

$$
\begin{equation*}
\lim _{\varepsilon_{k} \rightarrow 0} \sup \left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W} \leq\langle\chi, v\rangle_{W}+\langle f, \tilde{u}-v\rangle_{W}, \quad \forall v \in K \tag{2.30}
\end{equation*}
$$

Considering a sequence $v=v_{n} \rightarrow \tilde{u}$ as above we obtain

$$
\lim _{\varepsilon_{k} \rightarrow 0} \sup \left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W} \leq\langle\chi, \tilde{u}\rangle_{W}
$$

From the monotonicity of $B$ we have

$$
\left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W} \geq\left\langle B u_{\varepsilon_{k}}, v\right\rangle_{W}+\left\langle B v, u_{\varepsilon_{k}}-v\right\rangle_{W}, \quad \forall v \in W
$$

Then

$$
\begin{equation*}
\lim _{\varepsilon_{k} \rightarrow 0} \inf \left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W} \geq\langle\chi, v\rangle_{W}+\langle B v, \tilde{u}-v\rangle_{W}, \quad \forall v \in W \tag{2.31}
\end{equation*}
$$

It follows - taking $v=\tilde{u}$ - that

$$
\lim _{\varepsilon_{k} \rightarrow 0}\left\langle B u_{\varepsilon_{k}}, u_{\varepsilon_{k}}\right\rangle_{W}=\langle\chi, \tilde{u}\rangle_{W}
$$

From (2.31) we derive

$$
\langle\chi-B v, \tilde{u}-v\rangle_{W} \geq 0, \quad \forall v \in W
$$

Replacing $v$ by $\tilde{u}+t w$ and letting $t \rightarrow 0$ we obtain

$$
\langle\chi-B \tilde{u}, w\rangle_{W} \geq 0, \quad \forall w \in W
$$

i.e. $\chi=B \tilde{u}$. It follows that the whole sequence $B u_{\varepsilon_{k}}$ converges toward $B \tilde{u}$. Moreover (2.30) becomes

$$
\langle B \tilde{u}, v-\tilde{u}\rangle_{W} \geq\langle f, v-\tilde{u}\rangle_{W}, \quad \forall v \in K
$$

Since $\bar{K}^{W}$ is closed - weakly closed - one has $\tilde{u} \in \bar{K}^{W}$ and the above inequality holds also for every $v \in \bar{K}^{W}$. This completes the proof of the theorem.

Remark 4. (i) We have proved that the only possible limits for the subsequences of $\left(u_{\varepsilon}\right)_{\varepsilon}$ are solutions of the variational inequality (2.28). In particular if the solution is unique one has

$$
u_{\varepsilon} \rightharpoonup \tilde{u} \text { in } W, \quad B u_{\varepsilon} \rightharpoonup B \tilde{u} \text { in } W^{\prime}
$$

This is the case when $B$ is strictly monotone.
(ii) In the case where $K=V \cap W$ then $\bar{K}^{W}=W$ and $\tilde{u}$ is solution to the equation

$$
B \tilde{u}=f .
$$

As a corollary we have
Corollary 1. (i) Suppose that $A$ is strongly coercive in the sense that

$$
\begin{equation*}
\langle A v, v\rangle_{V} \geq \lambda|v|_{V}^{\alpha}, \quad \forall v \in V, \tag{2.32}
\end{equation*}
$$

for some constants $\lambda>0$ and $\alpha>1$, then one has

$$
\begin{equation*}
\varepsilon^{1 / \alpha} u_{\varepsilon} \rightarrow 0 \text { in } V . \tag{2.33}
\end{equation*}
$$

(ii) If $B$ is strongly monotone in the sense that for some $\delta>0$ and $\beta>1$

$$
\begin{equation*}
\langle B u-B v, u-v\rangle_{W} \geq \delta|u-v|_{W}^{\beta}, \quad \forall v, u \in W \tag{2.34}
\end{equation*}
$$

then the solution $\tilde{u}$ of (2.28) is unique and one has

$$
u_{\varepsilon} \rightarrow \tilde{u} \quad \text { in } W .
$$

Proof. (i) follows directly from

$$
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \geq \lambda \varepsilon\left|u_{\varepsilon}\right|_{V}^{\alpha}
$$

and Theorem 2-(iv).
For (ii) one has by (2.34) and since $u_{\varepsilon} \in K$

$$
\begin{aligned}
\delta\left|\tilde{u}-u_{\varepsilon}\right|_{W}^{\beta} & \leq\left\langle B \tilde{u}-B u_{\varepsilon}, \tilde{u}-u_{\varepsilon}\right\rangle_{W} \\
& \leq\left\langle f, \tilde{u}-u_{\varepsilon}\right\rangle_{W}-\left\langle B u_{\varepsilon}, \tilde{u}-u_{\varepsilon}\right\rangle_{W} \\
& =\left\langle f, \tilde{u}-u_{\varepsilon}\right\rangle_{W}+\left\langle B u_{\varepsilon}, u_{\varepsilon}\right\rangle_{W}-\left\langle B u_{\varepsilon}, \tilde{u}\right\rangle_{W} \rightarrow 0
\end{aligned}
$$

by (2.29).
Remark 5. Assuming only the basic coerciveness (2.3) of A, the convergence result (2.16) is sharp since if a approaches 1 in (2.33) the exponent of $\varepsilon$ tends to 1 .

In the following corollary some monotonicity property of $\left(u_{\varepsilon}\right)_{\varepsilon}$ is shown.
Corollary 2. Let $\varepsilon>\varepsilon^{\prime}>0$ then

$$
\begin{equation*}
\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V} \leq\left\langle A u_{\varepsilon}, u_{\varepsilon^{\prime}}\right\rangle_{V} . \tag{2.35}
\end{equation*}
$$

Proof. Indeed, set $v=u_{\varepsilon}$ (resp. $v=u_{\varepsilon^{\prime}}$ ) in (2.10), written for $\varepsilon$ (resp. $\varepsilon^{\prime}$ ), we get

$$
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V}-\varepsilon^{\prime}\left\langle A u_{\varepsilon^{\prime}}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V}+\left\langle B u_{\varepsilon}-B u_{\varepsilon^{\prime}}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{W} \leq 0 .
$$

Using the monotonicity of $A$ and $B$, it comes

$$
\begin{aligned}
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V} & \leq \varepsilon^{\prime}\left\langle A u_{\varepsilon}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V}-\varepsilon^{\prime}\left\langle A u_{\varepsilon}-A u_{\varepsilon^{\prime}}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V} \\
& \leq \varepsilon^{\prime}\left\langle A u_{\varepsilon}, u_{\varepsilon}-u_{\varepsilon^{\prime}}\right\rangle_{V} .
\end{aligned}
$$

Then (2.35) follows, since $\varepsilon>\varepsilon^{\prime}$.
Remark 6. The above characterization is more clear if $A$ is linear. For instance if $V$ is a Hilbert space and $A=I_{d}$ then (2.35) yields

$$
\left|u_{\varepsilon}\right|_{V} \leq\left|u_{\varepsilon^{\prime}}\right|_{V}, \text { for } \varepsilon^{\prime}<\varepsilon
$$

Next we pay attention to more regular problems, i.e. when some solutions of $(2.28)$ are in $V$.

Corollary 3. If the variational inequality (2.28) has a solution $\hat{u} \in K$ satisfying

$$
\begin{equation*}
\liminf \langle A u, u-\hat{u}\rangle_{V}>0 \quad \text { when }|u|_{V} \rightarrow+\infty, u \in K \tag{2.36}
\end{equation*}
$$

then $u_{\varepsilon}$ is bounded in $V$ and there exists always a sequence $u_{\varepsilon_{k}}$ such that

$$
\begin{equation*}
u_{\varepsilon_{k}} \rightharpoonup \tilde{u} \quad \text { in } V \text { and } W \text {, } \tag{2.37}
\end{equation*}
$$

where $\tilde{u} \in K$ is solution to (2.28), i.e. the accumulation points of $\left(u_{\varepsilon}\right)_{\varepsilon}$ are all in $K$ and solutions to (2.28).

In addition if $B$ satisfies (2.34), one has

$$
\begin{equation*}
\left|u_{\varepsilon}-\tilde{u}\right|_{W}=o\left(\varepsilon^{1 / \beta}\right) \tag{2.38}
\end{equation*}
$$

Proof. Taking $v=\hat{u}$ in (2.10) we derive

$$
\begin{align*}
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}-\hat{u}\right\rangle_{V} & \leq\left\langle f, u_{\varepsilon}-\hat{u}\right\rangle_{W}-\left\langle B u_{\varepsilon}, u_{\varepsilon}-\hat{u}\right\rangle_{W} \\
& \leq-\left\langle B u_{\varepsilon}-B \hat{u}, u_{\varepsilon}-\hat{u}\right\rangle_{W} \leq 0 \tag{2.39}
\end{align*}
$$

Thus $\left\langle A u_{\varepsilon}, u_{\varepsilon}-\hat{u}\right\rangle_{V} \leq 0$ for all $\varepsilon>0$, and

$$
\lim _{\varepsilon \rightarrow 0} \sup \left\langle A u_{\varepsilon}, u_{\varepsilon}-\hat{u}\right\rangle_{V} \leq 0
$$

By (2.36), $u_{\varepsilon}$ must be bounded in $V$ and one can find a sequence $\varepsilon_{k}$ such that

$$
u_{\varepsilon_{k}} \rightharpoonup \tilde{u} \quad \text { in } W, V \text { and } V \cap W .
$$

In fact, since $u_{\varepsilon_{k}}$ is bounded in $V, W$ and $W \cap V$ one can assume that -up to a subsequence-

$$
u_{\varepsilon_{k}} \rightharpoonup u \text { in } V, \quad u_{\varepsilon_{k}} \rightharpoonup u^{\prime} \text { in } W, \quad u_{\varepsilon_{k}} \rightharpoonup u^{\prime \prime} \text { in } V \cap W .
$$

If $h \in V^{\prime} \subset V^{\prime}+W^{\prime}$ one has

$$
\left\langle h, u_{\varepsilon_{k}}\right\rangle_{V \cap W} \rightarrow\langle h, u\rangle_{V \cap W}, \quad\left\langle h, u_{\varepsilon_{k}}\right\rangle_{V \cap W} \rightarrow\left\langle h, u^{\prime \prime}\right\rangle_{V \cap W}
$$

whence

$$
\langle h, u\rangle_{V}=\left\langle h, u^{\prime \prime}\right\rangle_{V}, \quad \forall h \in V^{\prime}
$$

Similarly one can show that

$$
\left\langle h, u^{\prime}\right\rangle_{W}=\left\langle h, u^{\prime \prime}\right\rangle_{W}, \quad \forall h \in W^{\prime}
$$

It follows that

$$
\begin{equation*}
u=u^{\prime}=u^{\prime \prime}=\tilde{u} \tag{2.40}
\end{equation*}
$$

and $\tilde{u}$ is necessarily a solution to (2.28).
For the last part of the theorem, since by the uniqueness of the solution of (2.28), $\hat{u}=\tilde{u}$, one has from (2.39)

$$
\begin{aligned}
\delta\left|\tilde{u}-u_{\varepsilon}\right|_{W}^{\beta} & \leq\left\langle B \tilde{u}-B u_{\varepsilon}, \tilde{u}-u_{\varepsilon}\right\rangle_{W} \\
& \leq-\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}-\tilde{u}\right\rangle_{V} \\
& =-\varepsilon\left\langle A u_{\varepsilon}-A \tilde{u}, u_{\varepsilon}-\tilde{u}\right\rangle_{V}+\varepsilon\left\langle A \tilde{u}, u_{\varepsilon}-\tilde{u}\right\rangle_{V} \\
& \leq \varepsilon\left\langle A \tilde{u}, u_{\varepsilon}-\tilde{u}\right\rangle_{V}=o(\varepsilon)
\end{aligned}
$$

and the result follows.
Remark 7. If we assume that $f=0, B(0)=0,0 \in K$ and $B$ satisfies a hypothesis as (2.32) then

$$
u_{\varepsilon} \rightarrow 0 \quad \text { in } W
$$

Indeed, taking $v=0$ in (2.10)

$$
\varepsilon\left\langle A u_{\varepsilon}, u_{\varepsilon}\right\rangle_{V}+\left\langle B u_{\varepsilon}, u_{\varepsilon}\right\rangle_{W} \leq 0
$$

and by the monotonicity of $A$ we have

$$
\lambda\left|u_{\varepsilon}\right|_{W}^{\beta} \leq \varepsilon\left\langle A u_{\varepsilon}-A(0), u_{\varepsilon}\right\rangle_{V}+\left\langle B u_{\varepsilon}, u_{\varepsilon}\right\rangle_{W} \leq-\varepsilon\left\langle A(0), u_{\varepsilon}\right\rangle_{V} .
$$

The convergence follows by Theorem 2.

## 3. Some applications

It is interesting to note that, using a priori estimates in the previous section, there is no need to have some compactness assumptions to pass to the limit in the nonlinear terms. In order to illustrate this we will consider here three nonlinear elliptic boundary value problems as examples of the abstract theory above. We will apply the theory to some anisotropic singular perturbations problems in the last two examples. To also see the power of our abstract analysis in general, we consider a very classical case of nonlinear obstacle problems.
3.1. Nonlinear obstacle problems. We denote by $a(\xi)=\left(a_{i}(\xi)\right)$ a continuous vector field in $\mathbb{R}^{n}$. We suppose that $a$ is such that for some $\lambda, \Lambda>0$ and $c \in \mathbb{R}$

$$
\begin{equation*}
a(\xi) \cdot \xi \geq \lambda|\xi|^{2}+c, \quad|a(\xi)| \leq \Lambda|\xi|, \quad \forall \xi \in \mathbb{R}^{n} \tag{3.1}
\end{equation*}
$$

and in addition that

$$
\begin{equation*}
(a(\xi)-a(\zeta)) \cdot(\xi-\zeta) \geq 0, \quad \forall \xi, \zeta \in \mathbb{R}^{n} \tag{3.2}
\end{equation*}
$$

Then, for $f \in L^{2}(\Omega)$ there exists a unique $u_{\varepsilon}$ solution to

$$
\left\{\begin{array}{l}
u_{\varepsilon} \in K_{0}=\left\{v \in H_{0}^{1}(\Omega) \mid v(x) \geq 0, \text { a.e. } x \in \Omega\right\}  \tag{3.3}\\
\varepsilon \int_{\Omega} a\left(\nabla u_{\varepsilon}\right) \cdot \nabla\left(v-u_{\varepsilon}\right) d x+\int_{\Omega} u_{\varepsilon}\left(v-u_{\varepsilon}\right) d x \\
\geq \int_{\Omega} f\left(v-u_{\varepsilon}\right) d x, \quad \forall v \in K_{0}
\end{array}\right.
$$

where $\Omega$ is a bounded open subset in $\mathbb{R}^{n}$. Then setting

$$
V=H_{0}^{1}(\Omega), \quad W=L^{2}(\Omega), \quad A u=-\operatorname{div}(a(\nabla u)), \quad B=I_{d}
$$

our results apply and we get that

$$
u_{\varepsilon} \rightarrow f^{+} \text {in } L^{2}(\Omega)
$$

where $f^{+}$(resp. $f^{-}$) denotes the positive (resp. negative) part of $f$. Indeed, thanks to Theorems 2, 3 and Corollary 1 we see that $u_{\varepsilon} \rightarrow \tilde{u}$ in $L^{2}(\Omega)$ where $\tilde{u}$ is the unique solution to

$$
\left\{\begin{array}{l}
\tilde{u} \in \bar{K}_{0}=\left\{v \in L^{2}(\Omega) \mid v(x) \geq 0, \text { a.e. } x \in \Omega\right\}  \tag{3.4}\\
\int_{\Omega} \tilde{u}(v-\tilde{u}) d x \geq \int_{\Omega} f(v-\tilde{u}) d x, \quad \forall v \in \bar{K}_{0}
\end{array}\right.
$$

But clearly

$$
\begin{aligned}
\int_{\Omega} f^{+}\left(v-f^{+}\right) d x & =\int_{\Omega}\left(f+f^{-}\right)\left(v-f^{+}\right) d x \\
& =\int_{\Omega} f\left(v-f^{+}\right) d x+\int_{\Omega} f^{-} v d x \\
& \geq \int_{\Omega} f\left(v-f^{+}\right) d x, \quad \forall v \in \bar{K}_{0}
\end{aligned}
$$

and $\tilde{u}=f^{+}$. As a corollary of Theorems 2,3 and Corollary 1 we can state the following.

Corollary 4. When $\varepsilon \rightarrow 0$, we have

$$
\begin{gathered}
u_{\varepsilon} \rightarrow f^{+} \text {in } L^{2}(\Omega), \quad \varepsilon u_{\varepsilon} \rightarrow 0 \text { in } H_{0}^{1}(\Omega), \\
-\varepsilon \partial_{x_{i}}\left(a\left(\nabla u_{\varepsilon}\right)\right) \rightarrow 0 \text { in } H^{-1}(\Omega), \quad i=1, \cdots, n . \\
\varepsilon \int_{\Omega} a\left(\nabla u_{\varepsilon}\right) \cdot \nabla u_{\varepsilon} d x \rightarrow 0 .
\end{gathered}
$$

Remark 8. Note that, as in (3.1), we may add a constant $c \in \mathbb{R}$ in (2.32) since it will be neglected once it is multiplied by $\varepsilon$ i.e.

$$
\langle A v, v\rangle_{V} \geq \lambda|v|_{V}^{\alpha}+c, \quad \forall v \in V
$$

Of course, here the strong convergence of $\sqrt{\varepsilon} \nabla u_{\varepsilon}$ comes from the last convergence in the above corollary, i.e.

$$
\sqrt{\varepsilon} \nabla u_{\varepsilon} \rightarrow 0 \quad \text { in } L^{2}(\Omega) .
$$

3.2. Semilinear elliptic problems. Let $\Omega$ be a bounded open subset of $\mathbb{R}^{n}$ with sufficiently smooth boundary. We split the components of a point $x \in \mathbb{R}^{n}$ into the $q$ first components and the $n-q$ last ones i.e.

$$
X_{1}=\left(x_{1}, \ldots, x_{q}\right) \quad \text { and } \quad X_{2}=\left(x_{q+1}, \ldots, x_{n}\right),
$$

where $q$ is a positive integer such that $q<n$. We denote by $\Pi_{X_{1}}$ (resp. $\Pi_{X_{2}}$ ) the orthogonal projection from $\mathbb{R}^{n}$ onto the space $X_{2}=0$ (resp. $X_{1}=0$ ). For any $X_{1} \in \Pi_{1}:=\Pi_{X_{1}}(\Omega)$ and $X_{2} \in \Pi_{2}:=\Pi_{X_{2}}(\Omega)$ we denote by $\Omega_{X_{1}}$ (resp. $\Omega_{X_{2}}$ ) the section of $\Omega$ above $X_{1}$ (resp. $X_{2}$ ) i.e.

$$
\Omega_{X_{1}}=\left\{X_{2} \mid\left(X_{1}, X_{2}\right) \in \Omega\right\}, \quad \Omega_{X_{2}}=\left\{X_{1} \mid\left(X_{1}, X_{2}\right) \in \Omega\right\} .
$$

With this notation we set

$$
\nabla u=\left(\partial_{x_{1}} u, \ldots, \partial_{x_{n}} u\right)^{T}=\binom{\left(\partial_{x_{1}} u, \ldots, \partial_{x_{q}} u\right)^{T}}{\left(\partial_{x_{q+1}} u, \ldots, \partial_{x_{n}} u\right)^{T}}=\binom{\nabla_{X_{1}} u}{\nabla_{X_{2}} u} .
$$

We consider the following semilinear elliptic problem

$$
\left\{\begin{array}{l}
-\varepsilon \Delta_{X_{1}} u_{\varepsilon}-\Delta_{X_{2}} u_{\varepsilon}+g\left(x, u_{\varepsilon}\right)=f \quad \text { in } \Omega,  \tag{3.5}\\
u_{\varepsilon} \in H_{0}^{1}(\Omega) \cap L^{p}(\Omega),
\end{array}\right.
$$

where

$$
\begin{aligned}
\Delta_{X_{1}}= & \sum_{i=1}^{i=q} \frac{\partial^{2}}{\partial^{2} x_{i}}, \Delta_{X_{2}}=\sum_{i=q+1}^{i=n} \frac{\partial^{2}}{\partial^{2} x_{i}}, \\
& p>1, f \in L^{2}(\Omega)+L^{p^{\prime}}(\Omega),
\end{aligned}
$$

where $p^{\prime}$ is the conjugate of $p$. In order to apply the abstract approach we assume that $g: \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a Carathédeory function and nondecreasing in the second variable i.e.

$$
\begin{aligned}
x & \mapsto g(x, t) \text { is measurable on } \Omega, \forall t \in \mathbb{R}, \\
t & \mapsto g(x, t) \text { is continuous and nondecreasing on } \mathbb{R} \text { for a.e. } x \in \Omega
\end{aligned}
$$

and there exist $c, c^{\prime} \geq 0$, such that

$$
\begin{array}{ll}
|g(x, t)| \leq c|t|^{p-1}+c^{\prime}, & \forall t \in \mathbb{R}, \text { a.e. } x \in \Omega, \\
g(x, t) t \geq|t|^{p}, & \forall t \in \mathbb{R}, \text { a.e. } x \in \Omega . \tag{3.7}
\end{array}
$$

It is clear that if $u \in L^{p}(\Omega)$ then $g(\cdot, u(\cdot)) \in L^{p^{\prime}}(\Omega)$. So $g$ defines an operator (still labelled by $g$ ) from $L^{p}(\Omega)$ into $L^{p^{\prime}}(\Omega)$ by

$$
\begin{equation*}
u \mapsto g(\cdot, u(\cdot)), \tag{3.8}
\end{equation*}
$$

which is bounded, monotone and hemicontinuous. Then we choose the suitable Banach spaces

$$
V=\left\{\begin{array}{l|l}
u \in L^{2}(\Omega) & \begin{array}{l}
\nabla_{X_{1}} u \in\left[L^{2}(\Omega)\right]^{q}, \\
u\left(\cdot, X_{2}\right) \in H_{0}^{1}\left(\Omega_{X_{2}}\right), \text { a.e. } X_{2} \in \Pi_{2}
\end{array} \tag{3.9}
\end{array}\right\}
$$

equipped with the norm

$$
|v|_{V}:=\left|\nabla_{X_{1}} v\right|_{L^{2}(\Omega)}
$$

and

$$
W=\left\{\begin{array}{l|l}
u \in L^{2}(\Omega) \cap L^{p}(\Omega) & \begin{array}{l}
\nabla_{X_{2}} u \in\left[L^{2}(\Omega)\right]^{n-q}, \\
u\left(X_{1}, \cdot\right) \in H_{0}^{1}\left(\Omega_{X_{1}}\right), \text { a.e. } X_{1} \in \Pi_{1}
\end{array} \tag{3.10}
\end{array}\right\},
$$

equipped with the norm

$$
|v|_{W}:=\left|\nabla_{X_{2}} v\right|_{L^{2}(\Omega)}+|v|_{L^{p}(\Omega)} .
$$

We can easily check that $V$ and $W$ are separable reflexive Banach spaces. Next we set

$$
A=-\Delta_{X_{1}} \quad \text { and } \quad B=-\Delta_{X_{2}}+g(x, \cdot) .
$$

Then the operator $A: V \rightarrow V^{\prime}$ is linear, bounded and coercive. Since the operator $B: W \rightarrow W^{\prime}$ is a sum of a linear operator, satisfying the same properties as $A$, and the operator defined in (3.8), it is bounded, monotone and coercive. In this example the limit problem is defined for a.e. $X_{1} \in \Pi_{1}$ as

$$
\begin{cases}-\Delta_{X_{2}} \tilde{u}\left(X_{1}, \cdot\right)+g\left(\left(X_{1}, \cdot\right), \tilde{u}\left(X_{1}, \cdot\right)\right)=f\left(X_{1}, \cdot\right) & \text { in } \Omega_{X_{1}}  \tag{3.11}\\ \tilde{u}\left(X_{1}, \cdot\right)=0 & \text { on } \partial \Omega_{X_{1}} .\end{cases}
$$

Then it remains to precise the connection between the boundary conditions, which is the subject of the following proposition.

Proposition 1. Let $V$ and $W$ be the spaces defined in (3.9) and (3.10) respectively, then if the boundary of $\Omega$ is smooth we have

$$
V \cap W=H_{0}^{1}(\Omega) \cap L^{p}(\Omega)
$$

Proof. The first inclusion $H_{0}^{1}(\Omega) \cap L^{p}(\Omega) \subset V \cap W$ is easy. For $u \in H_{0}^{1}(\Omega) \cap$ $L^{p}(\Omega)$ there exists a sequence $\left(u_{n}\right)_{n} \subset \mathcal{D}(\Omega)$ such that $u_{n} \rightarrow u$ in $H_{0}^{1}(\Omega) \cap$ $L^{p}(\Omega)$. In particular we have

$$
\left|\nabla\left(u_{n}-u\right)\right|_{L^{2}(\Omega)} \rightarrow 0
$$

By the Lebesgue theorem we get - up to a subsequence - for a.e. $X_{1} \in \Pi_{1}$ and $X_{2} \in \Pi_{2}$

$$
\begin{aligned}
\left|\nabla\left(u_{n}\left(X_{1}, \cdot\right)-u\left(X_{1}, \cdot\right)\right)\right|_{L^{2}\left(\Omega_{X_{1}}\right)} & \rightarrow 0 \\
\left|\nabla\left(u_{n}\left(\cdot, X_{2}\right)-u\left(\cdot, X_{2}\right)\right)\right|_{L^{2}\left(\Omega_{X_{2}}\right)} & \rightarrow 0
\end{aligned}
$$

This means that $u \in V$ and $u \in W$.
For the converse inclusion, let $u \in V \cap W$ and consider the following elliptic problem

$$
\begin{cases}-\varepsilon \Delta v_{\varepsilon}+v_{\varepsilon}=u & \text { in } \Omega  \tag{3.12}\\ v_{\varepsilon}=0 & \text { on } \partial \Omega\end{cases}
$$

Since $\Omega$ is sufficiently regular and of course $V \cap W \subset H^{1}(\Omega) \cap L^{p}(\Omega)$, we have $v_{\varepsilon} \in H^{2}(\Omega)$. According to Corollary 1, we derive

$$
\begin{equation*}
v_{\varepsilon} \rightarrow u \text { in } L^{2}(\Omega) \tag{3.13}
\end{equation*}
$$

Then applying the Laplace operator to the first equation in (3.12) and taking $-v_{\varepsilon}$ as a test function, we obtain

$$
\varepsilon\left\langle\Delta^{2} v_{\varepsilon}, v_{\varepsilon}\right\rangle_{H_{0}^{1}(\Omega)}-\int_{\Omega} \Delta v_{\varepsilon} v_{\varepsilon} d x=-\left\langle\Delta u, v_{\varepsilon}\right\rangle_{H_{0}^{1}(\Omega)}
$$

It is clear that $\Delta u \in H^{-1}(\Omega), \Delta^{2} v_{\varepsilon} \in H^{-1}(\Omega)$ since

$$
\begin{equation*}
-\Delta v_{\varepsilon}=\frac{u-v_{\varepsilon}}{\varepsilon} \in H^{1}(\Omega) \tag{3.14}
\end{equation*}
$$

It follows that

$$
-\varepsilon \int_{\Omega} \nabla\left(\Delta v_{\varepsilon}\right) \cdot \nabla v_{\varepsilon} d x+\left|\nabla v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2}=\int_{\Omega} \nabla u \cdot \nabla v_{\varepsilon} d x
$$

whence

$$
\begin{align*}
-\varepsilon \int_{\Pi_{1}} \int_{\Omega_{X_{2}}} & \nabla_{X_{1}}\left(\Delta v_{\varepsilon}\right) \cdot \nabla_{X_{1}} v_{\varepsilon} d X_{1} d X_{2} \\
& -\varepsilon \int_{\Pi_{2}} \int_{\Omega_{X_{1}}} \nabla_{X_{2}}\left(\Delta v_{\varepsilon}\right) \cdot \nabla_{X_{2}} v_{\varepsilon} d X_{2} d X_{1}+\left|\nabla v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2} \\
& =\int_{\Omega} \nabla u \cdot \nabla v_{\varepsilon} d x \leq \frac{1}{2}|\nabla u|_{L^{2}(\Omega)}^{2}+\frac{1}{2}\left|\nabla v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2} \tag{3.15}
\end{align*}
$$

Since $v_{\varepsilon} \in H_{0}^{1}(\Omega)$ and $u \in V \cap W$ in (3.14), we deduce for a.e. $X_{1} \in \Pi_{1}$ and a.e. $X_{2} \in \Pi_{2}($ see $[5])$

$$
\Delta v_{\varepsilon}\left(X_{1}, \cdot\right) \in H_{0}^{1}\left(\Omega_{X_{2}}\right), \Delta v_{\varepsilon}\left(\cdot, X_{2}\right) \in H_{0}^{1}\left(\Omega_{X_{1}}\right)
$$

Thus we can rewrite (3.15) as

$$
\begin{aligned}
& 2 \varepsilon \int_{\Pi_{1}} \int_{\Omega_{X_{2}}} \Delta v_{\varepsilon} \Delta_{X_{1}} v_{\varepsilon} d X_{1} d X_{2} \\
& +2 \varepsilon \int_{\Pi_{2}} \int_{\Omega_{X_{1}}} \Delta v_{\varepsilon} \Delta_{X_{2}} v_{\varepsilon} d X_{2} d X_{1}+\left|\nabla v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2} \leq|\nabla u|_{L^{2}(\Omega)}^{2}
\end{aligned}
$$

whence

$$
\begin{equation*}
2 \varepsilon\left|\Delta v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2}+\left|\nabla v_{\varepsilon}\right|_{L^{2}(\Omega)}^{2} \leq|\nabla u|_{L^{2}(\Omega)}^{2} \tag{3.16}
\end{equation*}
$$

It follows that $v_{\varepsilon}$ is bounded in $H_{0}^{1}(\Omega)$, then -up to a subsequence- its weak limit is in $H_{0}^{1}(\Omega)$ and due to (3.13) this limit is $u$. Thus $u \in H_{0}^{1}(\Omega)$, which ends the proof of the proposition.

As it is known, we need a pointwise convergence to pass to the limit in the nonlinear term $g\left(\cdot, u_{\varepsilon}\right)$. But the estimates that one has, i.e.

$$
\left|\nabla_{X_{2}} u_{\varepsilon}\right|_{L^{2}(\Omega)},\left|u_{\varepsilon}\right|_{L^{p}(\Omega)} \quad \text { are bounded }
$$

are not sufficient to get the pointwise limit of $\left(u_{\varepsilon}\right)_{\varepsilon}$ since the embedding

$$
W \subset L^{2}(\Omega)
$$

is not compact. So in this case the monotonicity hypothesis is necessary and as an obvious consequence of Theorems 2, 3 and Corollary 1 we have

Corollary 5. When $\varepsilon \rightarrow 0$, we have

$$
u_{\varepsilon} \rightarrow \tilde{u}, \quad \nabla_{X_{2}} u_{\varepsilon} \rightarrow \nabla_{X_{2}} \tilde{u} \text { and } \sqrt{\varepsilon} \nabla_{X_{1}} u_{\varepsilon} \rightarrow 0 \text { in } L^{2}(\Omega)
$$

where $\tilde{u}$ and $u_{\varepsilon}$ are the solutions of (3.11) and (3.5) respectively. Moreover if $g$ is strongly monotone then we obtain.

$$
u_{\varepsilon} \rightarrow \tilde{u} \quad \text { in } L^{p}(\Omega) .
$$

Remark 9. Note that, even if $B$ is not strongly monotone, the first two convergences hold strongly. This is due to the following monotone type inequality

$$
\begin{aligned}
\left\langle\Delta_{X_{2}} v-\Delta_{X_{2}} u, v-u\right\rangle_{W} & +\int_{\Omega}(g(x, v)-g(x, u))(v-u) d x \\
& \geq\left|\nabla_{X_{2}}(v-u)\right|_{L^{2}(\Omega)}^{2}, \quad \forall u, v \in W
\end{aligned}
$$

3.3. $p$-Laplacian type problem. The second application of the abstract theory, in the anisotropic case, is the following quasilinear elliptic equation

$$
\begin{cases}-\varepsilon \Delta_{p_{1}, X_{1}} u_{\varepsilon}-\Delta_{p_{2}, X_{2}} u_{\varepsilon}=f & \text { in } \Omega  \tag{3.17}\\ u_{\varepsilon}=0 & \text { on } \partial \Omega\end{cases}
$$

where $p_{1}, p_{2}>1$ are real constants and $\Delta_{p_{1}, X_{1}}, \Delta_{p_{2}, X_{2}}$ are the $p_{i}$-Laplace operators in $X_{1}$ and $X_{2}$ respectively i.e.

$$
\begin{aligned}
\Delta_{p_{1}, X_{1}} \cdot & =\nabla_{X_{1}} \cdot\left(\left|\nabla_{X_{1}} \cdot\right|^{p_{1}-2} \nabla_{X_{1}} \cdot\right) \\
\Delta_{p_{2}, X_{2}} \cdot & =\nabla_{X_{2}} \cdot\left(\left|\nabla_{X_{2}} \cdot\right|^{p_{2}-2} \nabla_{X_{2}} \cdot\right)
\end{aligned}
$$

We assume that

$$
f \in L^{p_{2}^{\prime}}(\Omega)
$$

( $p_{2}^{\prime}$ is the conjugate of $p_{2}$ ). In this case we set

$$
V=\left\{\begin{array}{l|l}
u \in L^{p_{1}}(\Omega) & \begin{array}{l}
\nabla_{X_{1}} u \in\left[L^{p_{1}}(\Omega)\right]^{q} \\
u\left(\cdot, X_{2}\right) \in W_{0}^{1, p_{1}}\left(\Omega_{X_{2}}\right), \text { a.e. } X_{2} \in \Pi_{2}
\end{array}
\end{array}\right\}
$$

equipped with the norm

$$
|v|_{V}=\left|\nabla_{X_{1}} v\right|_{L^{p_{1}}(\Omega)}
$$

and

$$
W=\left\{\begin{array}{l|l}
\left.u \in L^{p_{2}}(\Omega) \left\lvert\, \begin{array}{l}
\nabla_{X_{2}} u \in\left[L^{p_{2}}(\Omega)\right]^{n-q} \\
u\left(X_{1}, \cdot\right) \in W_{0}^{1, p_{2}}\left(\Omega_{X_{1}}\right), \text { a.e. } X_{1} \in \Pi_{1}
\end{array}\right.\right\}, ~ \text {, },
\end{array}\right\}
$$

equipped with the norm

$$
|v|_{W}=\left|\nabla_{X_{2}} v\right|_{L^{p_{2}}(\Omega)} .
$$

We can easily show that $V$ and $W$ are separable reflexive Banach spaces. Then we define the operators $A: V \rightarrow V^{\prime}$ and $B: W \rightarrow W^{\prime}$ as

$$
A=-\Delta_{p_{1}, X_{1}}, \quad B=-\Delta_{p_{2}, X_{2}}
$$

It is easy to see that $A$ and $B$ are coercive, bounded and hemicontinuous. The monotonicity of $A$ and $B$ is shown by the following lemma (see $[2,12]$ ).

Lemma 1. For all $p>1$ and $\xi, \eta \in \mathbb{R}^{n}$, we have, for a constant $c_{p}>0$,

$$
\left(|\xi|^{p-2} \xi-|\eta|^{p-2} \eta\right) \cdot(\xi-\eta) \geq c_{p}\{|\xi|+|\eta|\}^{p-2}|\xi-\eta|^{2}
$$

If $p \geq 2$, then

$$
\left(|\xi|^{p-2} \xi-|\eta|^{p-2} \eta\right) \cdot(\xi-\eta) \geq c_{p}|\xi-\eta|^{p}
$$

where $|\cdot|$ is the usual Euclidean norm in $\mathbb{R}^{n}$ and "." is the scalar product.
Thus the operator $A$ (resp. $B$ ) is strictly monotone for all $p_{1}>1$ (resp. $p_{2}>1$ ) and strongly monotone if $p_{1} \geq 2$ (resp. $p_{2} \geq 2$ ). The limit problem is defined, for a.e. $X_{1} \in \Pi_{1}$, as

$$
\begin{cases}-\Delta_{p_{2}, X_{2}} \tilde{u}\left(X_{1}, \cdot\right)=f\left(X_{1}, \cdot\right) & \text { in } \Omega_{X_{1}}  \tag{3.18}\\ \tilde{u}\left(X_{1}, \cdot\right)=0 & \text { on } \partial \Omega_{X_{1}}\end{cases}
$$

Finally as in the previous subsection we can show that

$$
(V \cap W) \subset W_{0}^{1, \min \left(p_{1}, p_{2}\right)}(\Omega)
$$

More precisely we have
$V \cap W=\left\{u \in L^{\max \left(p_{1}, p_{2}\right)}(\Omega) \left\lvert\, \begin{array}{l}\nabla_{X_{1}} u \in\left[L^{p_{1}}(\Omega)\right]^{q}, \nabla_{X_{2}} u \in\left[L^{p_{2}}(\Omega)\right]^{n-q}, \\ \left.u\right|_{\partial \Omega}=0\end{array}\right.\right\}$,
which gives a sense to the boundary conditions. Then by Theorem 2, 3 and Corollary 1 we have

Corollary 6. For all $p_{1}, p_{2}>1$,

$$
\begin{array}{rlll}
u_{\varepsilon} & \rightharpoonup \tilde{u} & \text { in } & W \\
\varepsilon \nabla_{X_{1}} u_{\varepsilon} \rightarrow 0 & \text { in } & L^{p_{1}}(\Omega),  \tag{3.19}\\
\varepsilon \Delta_{p_{1}, X_{1}} u_{\varepsilon} \rightarrow 0 & \text { in } & V^{\prime}, \\
\Delta_{p_{2}, X_{2}} u_{\varepsilon} & \rightharpoonup f & \text { in } & W^{\prime},
\end{array}
$$

where $u_{\varepsilon}$ and $\tilde{u}$ are the solutions of (3.17) and (3.18) respectively. Moreover if $p_{1} \geq 2$ then

$$
\begin{equation*}
\varepsilon^{1 / p_{1}} \nabla_{X_{1}} u_{\varepsilon} \rightarrow 0 \quad \text { in } L^{p_{1}}(\Omega) \tag{3.20}
\end{equation*}
$$

and if $p_{2} \geq 2$ then

$$
\begin{equation*}
u_{\varepsilon} \rightarrow \tilde{u}, \nabla_{X_{2}} u_{\varepsilon} \rightarrow \nabla_{X_{2}} \tilde{u} \quad \text { in } L^{p_{2}}(\Omega) . \tag{3.21}
\end{equation*}
$$

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