

Stationarity preserving schemes for the linearized Euler equations in multiple spatial dimensions

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Euler equations

 $\partial_t \rho + \nabla \cdot (\rho \mathbf{v}) = 0$ $\partial_t(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v} + \frac{p}{\epsilon^2} \cdot \mathbf{1}) = 0$ $\partial_t e + \nabla \cdot (\mathbf{v}(e+p)) = 0$

Acoustic equations

 $\begin{array}{l} \text{Linearization} \\ \rightarrow \end{array} \quad \partial_t \mathbf{v} + \frac{\nabla p}{\epsilon^2} = 0 \\ \partial_t p + c^2 \nabla \cdot \mathbf{v} = 0 \end{array}$

Fourier transform: $q(t, \mathbf{x}) = \hat{q}(t) \exp(\mathbf{i}\mathbf{k} \cdot \mathbf{x})$

 $\Rightarrow \partial_t \hat{q} + i(\mathbf{J} \cdot \mathbf{k})\hat{q} = 0$

Summary

The linearized Euler equations possess a low Mach number limit. This serves as a guideline to the nonlinear case by the following result:

The ability of a numerical scheme to resolve the low Mach number limit is equivalent to preserving a discrete vorticity.



incompressible Euler equations

 $\nabla p = 0$ and $\nabla \cdot \mathbf{v} = 0$

 $\epsilon \to 0$

This allows to characterize all low Mach compliant schemes.

Continuous statements

The acoustic equations are an example of a

Linear hyperbolic system in multi-d

 $\partial_t q + \mathbf{J} \cdot \nabla q = 0$

Stationary states of linear acoustics:

 $\nabla \cdot \mathbf{v} = 0$ $\nabla p = 0$

Stationary states

- $det(\mathbf{J} \cdot \mathbf{k}) = 0 \Rightarrow$ stationary states exist
- their Fourier transform is the **right eigenvector** with eigenvalue 0
- If $det(\mathbf{J} \cdot \mathbf{k}) = 0$ independently of \mathbf{k} , then the stationary states are called

Vorticity: $\omega = \nabla \times \mathbf{v}$. For linear acoustics,

 $\partial_t \omega = 0$

Constant of motion

• $det(\mathbf{J} \cdot \mathbf{k}) = 0 \Rightarrow constant of motion exists$

Indeed, consider a **left eigenvector** Ω of

 $\mathbf{J} \cdot \mathbf{k}$ with eigenvalue 0, i.e.

$$\Omega(\mathbf{J}\cdot\mathbf{k})=0$$

Given initial data $q(0, \mathbf{x}) = \hat{q} \exp(\mathbf{i} \mathbf{k} \cdot \mathbf{x})$ there exist \hat{q}^0, \hat{q}^{\pm} such that

$$q(t, \mathbf{x}) = \hat{q}^0 + \hat{q}^{\pm} \exp\left(\mp \frac{c|\mathbf{k}|t}{\epsilon} + \mathbf{k} \cdot \mathbf{x}\right)$$

By reinterpreting $\frac{c}{\epsilon} \cdot t$ as $c \cdot \frac{t}{\epsilon}$ the low Mach number limit is equivalent to the limit of long times.

Vorticity preserving Stationarity preserving Low Mach compliant \Leftrightarrow \Leftrightarrow

In the discrete case, the **evolution matrix** \mathcal{E} (see Box below) plays the role of $\mathbf{J} \cdot \mathbf{k}$:

Discrete stationary states

- det $\mathcal{E} = 0$ independently of $\mathbf{k} \Rightarrow$ nontrivial discrete stationary states exist: stationarity preserving scheme.
- their Fourier transform is the **right eigenvector** with eigenvalue 0.
- all the analytic stationary states are captured^a in the discrete. (Both trivial and nontrivial!)
- ^{*a*} More precisely: The discrete stationary states are discretizations of all the analytic stationary states, not just of the subset of trivial

Numerical constant of motion

- det $\mathcal{E} = 0 \Rightarrow$ numerical constant of motion exists.
- its Fourier transform is the **left eigenvector** with eigenvalue 0.

For linear acoustics such schemes are called vorticity preserving.

Vorticity preserving schemes for linear acoustics have been studied among others in Morton & Roe 2001, Jeltsch & Torrilhon 2006, Mishra & Tadmor 2011.

- Limit of long time also in the discrete.
- von Neumann stability: non-stationary modes decay in time
- Thus all the limit states for $\epsilon \to 0$ are captured in the discrete: low Mach compliant scheme.

Discrete statements

References:

Wasilij Barsukow: Stationarity preserving schemes for multi-dimensional linear systems, 2017, preprint https://www.mathematik.uni-wuerzburg.de/~barsukow

Wasilij Barsukow: Stationarity and vorticity preservation for the linearized Euler equations in multiple spatial dimensions, Finite Volumes for Complex Applications VIII Methods and Theoretical Aspects, C. Cancès and P. Omnes (eds.), Springer Proceedings in Mathematics & Statistics 199, 2017

Evolution matrix • rectangular grid with spacing Δx_m in *m*-th spatial direction, $m = 1, \ldots, d$ • Each cell has a unique index $I \in \mathbb{Z}^d$, q_I is the value of q in cell I. • k_m and I_m are the components of **k** and *I* in *m*-th direction Fourier ansatz: $q_I = \hat{q} \exp\left(i\sum_{m=1}^{a} I_m k_m \Delta x_m\right) = \hat{q} \prod_{m=1}^{a} t_m^{I_m}$ with the translation factor $t_m := \exp(ik_m \Delta x_m)$. The semidiscrete scheme $\partial_t q_I + \sum \alpha_S q_{I+S} = 0$ upon the Fourier transform amounts to $\partial_t \hat{q} + \mathcal{E} \hat{q} = 0$ with the time evolution governed by the **evolution** matrix $\mathcal{E} = -\sum i \alpha_S \prod t_m^{S_m}$. $S \in [-N,N]^d$ m=1